

## **D7000 SERIES USERS MANUAL**



Version 1.5

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#### WARRANTY

DGH warrants each D7000 series module to be free from defects in materials and workmanship under normal conditions of use and service and will replace any component found to be defective, on its return to DGH, transportation charges prepaid within one year of its original purchase. DGH assumes no liability, expressed or implied, beyond its obligation to replace any component involved. Such warranty is in lieu of all other warranties expressed or implied.

#### WARNING

The circuits and software contained in D7000 series modules are proprietary. Purchase of these products does not transfer any rights or grant any license to the circuits or software used in these products. Disassembling or decompiling of the software program is explicitly prohibited. Reproduction of the software program by any means is illegal.

As explained later in this document, all setups are performed entirely from the outside of the D7000 module. There is no need to open the module because there are no user-serviceable parts inside. Removing the cover or tampering with, modifying, or repairing by unauthorized personnel will automatically void the warranty. DGH is not responsible for any consequential damages.

#### **RETURNS**

When returning products for any reason, contact the factory and request a Return Authorization Number and shipping instructions. Write the Return Authorization Number on the outside of the shipping box. DGH strongly recommends that you insure the product for value prior to shipping. Items should not be returned collect as they will not be accepted.

#### **CONTACT INFORMATION**

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Attn: RMA#

### 1.0 Introduction

The D7000 series modules are a complete family of Ethernet based data acquisition modules. The product family includes multi-channel analog input measurement modules, multiple channel analog output modules, discrete digital input and discrete digital output modules.

The D7000 series modules communicate using several different Ethernet protocols, including the Modbus TCP/IP protocol. This protocol is very popular in the data acquisition and process control industries. Modbus TCP/IP is supported by all commercial data acquisition software programs in the market place. Thus, providing instant connectivity to wide variety of software programs for almost any budget.

Data values can also be read from the modules using the REST (Representational State Transfer) protocol. Devices that support the REST protocol often use the HTTP protocol to transmit read and write data requests, or to delete data. The REST protocol is a lightweight alternative to other protocols and services such as RPC (Remote Procedure Calls) and Web Services (SOAP, WSDL, et al.). Later, we outline how simple the REST protocol really is. Note: The REST is not a "standard".

#### **Model Numbers**

The D7000 series consists of three different types of modules: Analog Input modules, an Analog Output module and three discrete digital input/output modules. The analog input modules contain seven differential input channels and can measure DC voltages, 4-20mA current loops and thermocouples. Each input channel is user configurable for a unique input range.

The D7100 module measures seven differential DC voltage signals and offers five different measurement ranges, including +/-25mV, +/-50mV, +/-100mV, +/-1V, +/-5V and +/-10V.

The D7200 module measures seven differential 4-20mA current loops using a +/-20mA input range.

The D7300 module measures seven differential thermocouples and supports eight different thermocouple types, including the J, K, T, E, R, S, B and C types.

The D7400 module can measure seven differential DC voltages, 4-20mA current and thermocouples. The DC voltage ranges and thermocouple types are the same as listed above and the range of each channel is user-selectable.

The D7500 analog output module contains two output channels for generating either a DC voltage or current output. Each analog output channel is user-selectable as either a voltage output or a current output. The analog output signals can be used to control items such as motors, valves, and other control devices. Each analog output channel also contains a programmable communications watchdog timer for instances when communications to the module is lost.

The D7710 digital input module contains fifteen discrete inputs for monitoring switches or contact closures from field devices. The digital inputs contain internal 22K ohm pull-up resistors from each bit on the module connector to +5Vdc. Thus, there is no need for external biasing resistors.

The D7720 digital output module contains fifteen discrete digital outputs that are open-collector outputs that can be connected up to 30Vdc and can sink 100mA per bit. The open-collector allows the modules to be used in a wider variety of control applications. The digital output module also contains a programmable communications watchdog timer that will return the discrete digital outputs to a known safe condition in the event of a communications link failure.

The D7730 digital input / output module contains eight digital outputs and seven digital inputs. The input and output bits contain the same specifications as the D7710 and D7720 described above.

#### **Communications**

The D7000 series modules Ethernet I/O modules connect directly to a LAN (local area network) or WAN (wide area network) using an Ethernet RJ45 connection. An Ethernet CAT-5 cable is used to connect each module to a network router or hub. Once the module is connected to the router or hub, apply power to the module.

#### **Network IP Address**

The D7000 requires an Ethernet network IP address in order to communicate. The IP address can be specified using either a Static or a DHCP IP address. Static IP addresses are unique network address values assigned by the user. Care must be taken to ensure that each Static IP is unique to the network. Knowledge of the network addressing is required to prevent duplication of address values. If necessary, consult your network system administrator for a unique IP address value.

Dynamic Host Configuration Protocol (DHCP) IP addresses are assigned automatically by a DHCP server that is normally located inside of the network router. DHCP ensures that every device on the network contains a unique network address. Using DHCP is the easiest method of connecting devices to a network and requires no knowledge of the network addressing.

DHCP is the easiest method of connecting devices to a network. However, it may not be the best for an industrial application. Especially since a new IP address is assigned when the device is connected to the network or powered on. If the IP address changes when the device is connected to the network then supervisory control software may lose connection with the device when the address changes.

Consider using a Static IP address in applications where the device IP address is entered verbatim in to the host supervisory software.

#### **Protocols**

The D7000 series modules use two different protocols for communications with a host supervisory computer. The two protocols are the Modbus TCP/IP protocol and the REST protocol.

#### Modbus TCP/IP Protocol

The D7000 primary method of communications is the Modbus TCP/IP protocol. The Modbus TCP/IP protocol is a Master / Slave protocol. Typically, a host computer transmits a command over a local area network to a slave device. The command is considered as a request for the module to perform a specific task or function. The module will perform the task and then return any required data. The D7000 is considered a Modbus TCP/IP slave device and supports many of the standard Modbus Functions. See the list of supported functions in Chapter 4.0 of this document.

### **REST Protocol**

The D7000 series supports the REST protocol for communicating data values back to a host computer. The REST protocol is a version of HTTP protocol that can be used to read data values, peak and valley readings, scale minimum and maximums, and the channel range settings. The amount of items returned is dependent upon the module type, analog input, analog output or digital I/O. Refer to the detailed description of the REST protocol in Chapter 4.0 of this document.

#### **Operating Modes**

The D7000 series contains several different modes of operation. First, the module can operate as a simple measurement or control module where a supervisory computer reads or writes commands to the device. This would be considered the normal mode of operation.

#### Peer-To-Peer

The D7000 series contains a Peer-To-Peer mode where two modules can be paired together and communicate over a network. In Peer-to-Peer mode, an analog input module can be paired with an analog output module. Or, a digital input module can be paired with a digital output module. One module considered the sender and the other is considered the receiver. This mode can be used to duplicate analog or digital signals in multiple locations over a network. The modules use the Modbus TCP/IP protocol to communicate. The data values are communicated at a user-specified time interval.

### Thingspeak.Com Cloud Service

The D7000 series support connections to the Thingspeak.Com cloud service. Sensor data measured with the D7000 can be uploaded and stored on the Thingspeak cloud service. The data values are stored on the Thingspeak cloud servers indefinitely and can be exported at anytime to a local disk file using a Comma-Separated-Value file format. The local disk file can then be imported into a spreadsheet program for future analysis. The data values are communicated at a user-specified time interval.

#### **Email On Limits**

The D7000 series can send email messages based on signal limits.

See Chapter 4.0 for a more detailed explanation of the protocols and operating modes.

### 2.0 Web Browser Configuration

#### **Getting Started**

The D7000 series modules contain a web browser interface for configuring the device. A menu bar is located at the top of each web page. The "Configuration" menu selection links to a web page that contains all the user-selectable options for each module. Other individual web pages are used to display module status and the configuration values. All web pages can be viewed using any the common web browsers found on most computers today. Examples are Internet Explorer, FireFox, Chrome and others.

The browser interface contains many web pages that display system status and configuration values for specific module features. There is a menu bar at the top of each page and one menu selection links to the module "Configuration" page. The Configuration page selection allows a user to change or adjust any of the user-selectable options within the device. This web page can be configured as accessible to anyone or password protected to prevent unauthorized changes.

### **Network Configuration**

The D7000 series modules require a network IP address in order to communicate. There are two methods of providing an IP address. The most common method is to use DHCP where a router automatically assigns a network address. The other method is to specify a static or fixed IP address manually. When using a static IP address care must be taken to ensure that a unique IP address is assigned to each module. Using the same IP address on multiple modules or devices will result in communications fault conditions.

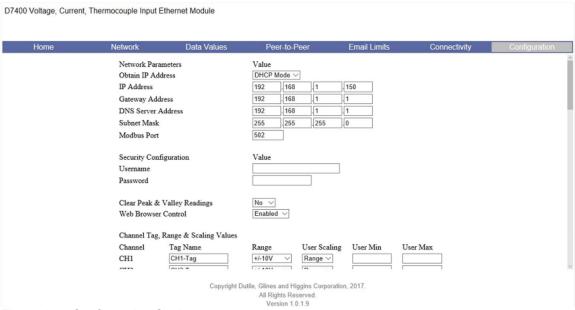


Figure 1.0 Configuration Settings

The D7000 series modules are shipped with DHCP automatic network configuration enabled and they will obtain their IP addresses from a network router. It may be necessary to view the "connected devices" table on the network router in order to determine the IP address assigned to each device.

#### **Username and Password**

The D7000 series modules can utilize simple Username and Password security to protect the Configuration screen values. When values are entered into the Username and Password text boxes then the D7000 will generate a Login box before entering the Configuration screen. All other web pages will only display values and therefore are not protected by a username and password login.

#### Clear Peak & Valley Readings

The D7000 series modules Peak and Valley readings are the highest and lowest values that have been detected for each channel during normal operation. The D7000 series contain a micro controller to perform the Ethernet processing functions and a signal processing controller handles all of the analog I/O or digital I/O processing. The Ethernet controller reads the signal processor data values and then compares each channel reading the channel Peak and Valley readings. When the update is complete the new Peak and Valley readings are stored in EEPROM for review at a later time.

The Clear Peak & Valley Readings drop down listbox feature allows all of the peak and valley readings to be removed from memory. If "yes" is selected then the Peak and Valley readings will be erased when the "Apply" button is pressed at the bottom of the "Configuration" page. The value will default back to "No" when the web page is reloaded.

#### Web Browser Control

The Web Browser Control feature allows a user to manage the device through a Web Browser. Select Enable or Disable for the desired operation during normal operation. Select Enable and allow the module to be managed and configured using a web browser. Select Disable to turn off the web browser management.

As a general practice, disabling the web browser control during normal operation will allow the module to process more requests from other functions. It will also limit user access lower the possibility of unauthorized changes. The web browser management can be turned back on using the D6000 Utility Software.

#### **Channel Tag, Range and Scaling Values**

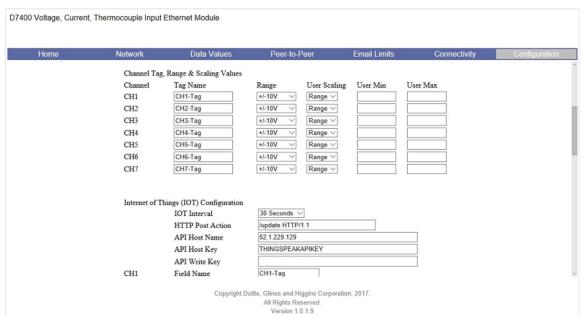


Figure 2.0 Configuration Settings, Continued.

A Tag Name can be associated with each analog and digital I/O channel in the D7000 series modules. The Tag name is an arbitrary string of characters that might represent the control function being performed (by that channel). For example, a digital output may have an assigned Tag name of "Start Motor". The Tag Name values are also displayed on several of the web browser pages. Empty Tag names may prevent associated channel values from being displayed in certain configurations.

A Range drop down listbox is provided on the web browser configuration page to specify the analog voltage or current range of each channel. Select the analog range and these values will be activated and stored when the APPLY button is depressed at the bottom of the page.

A Scaling drop down list box is provided on the web browser configuration page to specify the scaling technique for each analog channel. The Scaling list box selections include User specified scaling values or the raw 16-bit unsigned integer Modbus values.

Two text boxes are also provided to hold the user specified minimum and maximum scaling values. When User scaling is selected then the data values displayed in the web pages will be linearly scaled such that the user minimum equals minus full-scale and user maximum equals positive full-scale. All data values in between are linearly interpolated.

If Raw Scaling is specified then the Raw Modbus data values between 0 and 65535 will be displayed. These values represent the percentage of the full scale range.

### Internet of Things (IOT) Configuration

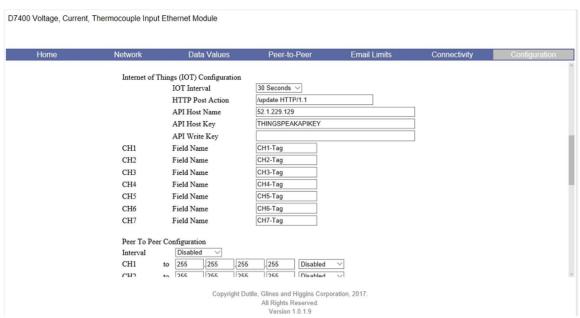


Figure 3.0 Configuration Settings, Continued.

The Internet of Things (IOT) configuration values must be specified correctly in order to begin uploading module data values to the Thingspeak.Com cloud service. See the working configuration values in Figure 3.0 above.

The IOT Interval is the user-specified time interval that the module will upload data values to Thingspeak.com.

The HTTP Post Action is the method used upload data values to the cloud service.

The API Host Name is specified by the cloud service. It can be in the form of a domain name such as 'api.thingspeak.com'. Or, it can be an IP address value as illustrated in Figure 3.0 above.

The API Host Key and Write Key are values specified by the cloud service and are specific to the device when defined in the cloud.

A Field Name can be associated with each analog and digital I/O channel. The Tag name is an arbitrary string of characters that might represent the control function being performed (by that channel). For example, a digital output may have an assigned Tag name of "Start Motor". The Tag Name values are also displayed on several of the web browser pages. Empty Tag names may prevent associated channel values from being uploaded in certain configurations.

### **Peer-To-Peer Configuration**

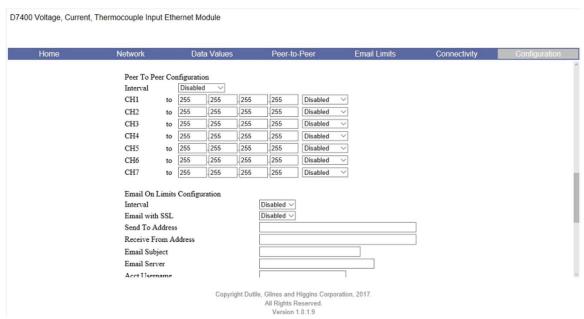


Figure 4.0 Configuration Settings, Continued.

The D7000 series Peer-To-Peer is enabled by selecting an Interval Time other than "Disabled" as illustrated in Figure 4.0 above.

In Peer-to-Peer Mode, each analog or digital channel can be transmitted individually to another D7000 module by specifying the receiving module IP address. The module must be of the same signal type. Meaning, analog input modules transmit to analog output modules. Likewise with digital input to digital output modules.

Analog Input modules can send to either Channel #1 or Channel #2 on a two channel analog output module. Specify CH1 or CH2 using the drop down list box to the right of the IP address. Unused channels can be disabled by selecting "Disabled" in the drop down list box.

When configuring the analog output or digital output modules, enter the IP address of the sending module.

### **Email on Limits Configuration**

Home	Network	Data Values	Peer-to-Peer	Email Limits	Connectivity	Configuration		
	Email On Lim	its Configuration						
	Interval		Disabled ∨					
	Email with SS	L	Disabled ∨					
	Send To Addre	Send To Address						
	Receive From	Address						
	Email Subject							
	Email Server							
	Acct Usernam	e						
	Acct Password	1						
	Email Port		110					
	CH1		Disabled ∨ 0.00					
	CH2		Disabled ∨ 0.00					
	CH3		Disabled V 0.00					
	CH4		Disabled V 0.00					
	CH5		Disabled V 0.00					
	CH6		Disabled V 0.00					
	CH7		Disabled V 0.00					
	CH5 CH6		Disabled $\vee$ 0.00 Disabled $\vee$					

Figure 5.0 Configuration Settings, Continued.

# IMPORTANT: The D7000 series "Email on Limits" mode of operation requires access to an external email server. The module "does not" contain an internal mail server!!

Configuration of the "Email on Limits" mode requires the user to have an email account and knowledge of the account SMTP server settings. Free email accounts can be obtained on the internet from several providers. This mode has been successfully tested with a account. We recommend that users do not use their personal or work email accounts in this mode.

The D7000 series Email on Limits mode is enabled by selecting an Interval Time other than "Disabled" as illustrated in Figure 5.0 above.

The eight email account settings underneath the Interval list box must be obtained from the email service that was chosen for use in this mode. See the Gmail settings below that were used to perform product testing.

PARAMETERS	GMAIL
Email with SSL	
Send To Address	
Receive From Address	
Email Subject	
Email Server	
Email Acct Username	
Email Acct Password	
Email Port	

Figure 6.0 Configuration Settings, Continued.

Each D7000 series analog input module contains a drop down list box for each channel that determines the limit testing method that will be performed. There are four different comparisons that can be selected: disabled, equal to a value, less than a value or greater than a value. Select the channel comparison test required or disabled so that no comparison testing is performed.

#### **REST Protocol**

The D7000 supports the REST protocol for communicating data values back to a host computer. The REST protocol is a version of HTTP protocol that can be used to read data values, peak and valley readings, scale minimum and maximums, and the channel range settings. Enable or Disable the REST protocol using the drop down list box.

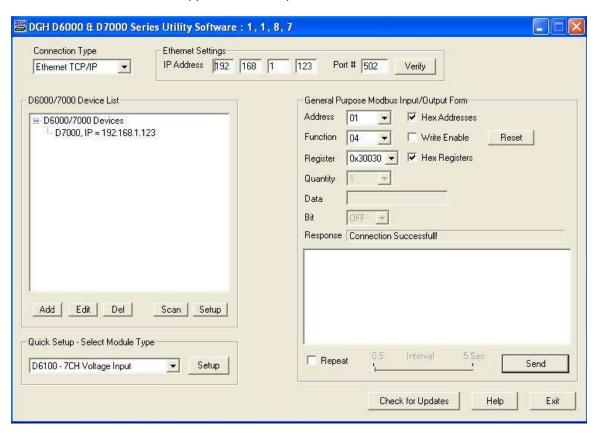
### 3.0 Utility Software

The D7000 series modules require a software program to change the content in the setup registers. Since the modules communicate via the Modbus TCP/IP protocol, a Modbus Master program or the DGH D7000 series Utility Software will be required to change the module configuration.

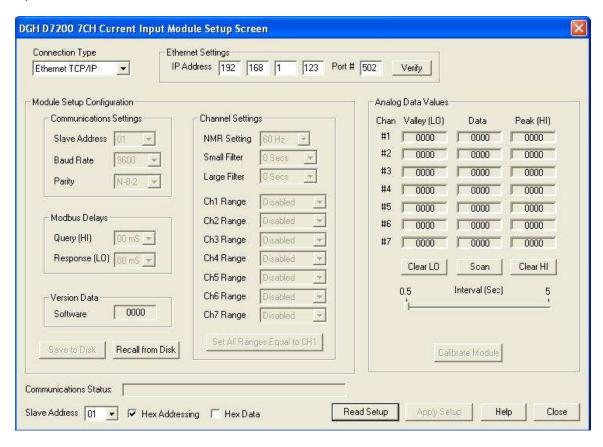
The DGH D6000/D7000/D8000 Series Utility Software is the best program to use when configuring a module. The utility software reads the module information, displays the information in easy to understand terms, allows changes to be made via drop-down list boxes and then writes the new values back to the module. The module parameters can also be stored to disk and recalled at a later date.

The Utility Software is provided free of charge on CDROM with a purchase order and the latest version is always downloadable from <a href="www.dghcorp.com">www.dghcorp.com</a>. The utility software runs on Windows based computers. Simply insert the CDROM into the CDROM drive, or download the Setup.Exe installation program from our website, and then run the installer. The software will install and create a menu section called "DGH DATA ACQUISITION" and the D6000 Utility Software will be located under that selection.

From the computer desktop click the "start" button, select "all programs", select "DGH Data Acquisition" and then select "D6000 Series Utility Software" to run the utility software. When the software opens the first step is to set the "Connection Type" drop down list box to "Ethernet TCP/IP". Then enter the IP address of the D7000 series module and press the "Verify" button to see if the Utility Software can connect to the module. If the connection was successful then "Connection Successful" will appear in the Response block. See below.



After a successful connection test has been performed then the module can be configured. Select the type of module using the drop-down list box under "Quick Setup" in the lower left hand corner of the screen. Then press the "Setup" button and a new screen (see below) will appear that contains list of all the user-selectable module values. Several different screens will appear for the different types of module that are connected. The screen below is for a seven channel current input module.



Ensure that the Module Address in the lower left corner remains at "01" and then press the "Read Setup" button. The screen will populate with the existing module configuration data.

The user-selectable values will be displayed in an easy to understand format and new selections can be made using the drop-down list boxes. The drop-down list boxes make the configuration process easy and accurate because erroneous values cannot be entered.

Once the new module configuration settings have been changed to meet the application requirements then press the "Apply" button to transmit the new settings.

#### Scan Module

After the module has been properly configured, the software can scan the modules for their present data values in order to verify each channel is functioning properly. This feature is a good troubleshooting or verification tool when the analog signals are connected to the module.

The analog input screens contain a "Scan" button that will start the scanning process. Each data channel is read by requesting the data values from data registers within the module. The analog input data register locations can be found in the Modbus Register map and the data in each register is specific to the module type and channel range specified.

#### **Data Values**

The data values are returned in hexadecimal percentage of Full Scale format where a value of 0x0000 represents the minus full scale input of the module. A value of 0xffff represents the positive full scale input of the module. These values can be used as check to ensure that the channels are operating properly when analog input signals are applied to the input terminals.

The data values can also be displayed as a numerical value. The utility software knows the plus and minus full scale limits for each channel. Using the raw hexadecimal percentage of full scale data values the software can convert these readings to millivolts, milliamps, or temperature readings. Simply uncheck the "Display Hex Values" selection underneath the channel readings to display the numeric values.

The scanning process can also log and display the highest (peak) and lowest (valley) readings that were recorded during the scanning process. This is just for indication purposes only.

A scan interval slide control is also provided to speed up or slow down the scanning process. This slide control allows the channels to be scanned at intervals from 0.5 to 5 seconds.

### 4.0 Protocols and Operating Modes

The D7000 series module contains an Ethernet RJ-45 Ethernet interface for communications. They support two different communications protocols and multiple operating modes.

#### Modbus TCP/IP Protocol

The primary communications protocol is the Modbus TCP/IP Ethernet protocol. This protocol can communicate over a local area network or the internet. It is widely recognized and supported by all data acquisition and SCADA software programs in the marketplace. Thus, providing instant connectivity to many software programs. See more detailed information about the Modbus TCP/IP protocol further in this chapter.

#### **REST Protocol**

The D7000 supports the REST protocol for communicating data values back to a host computer. The REST protocol is a version of HTTP protocol that can be used to read data values, peak and valley readings, scale minimum and maximums, and the channel range settings. The amount of items returned is dependent upon the module type, analog input, analog output or digital I/O. See more detailed information about the REST protocol further in this chapter.

### **Normal Operating Mode**

The D7000 series modules "normal mode" of operation would be communicating data values to a supervisory host computer using the Ethernet Modbus TCP/IP protocol. A host computer would perform all the data reading and writing with standard Modbus commands known as function. Each of the supported functions and their purpose is further in this chapter.

#### Peer-To-Peer Mode

The D7000 series Peer-to-Peer mode allows an analog input module to send data values to an analog output module in another location. Likewise with digital input and digital output modules. The sending modules perform a measurement on a specific channel and the transmit that value to analog or digital output module. Thus, recreating the measured signal in another location, possibly within the same plant, or another remote location. The signal values are communicated using the Modbus TCP/IP protocol.

### **Cloud Publishing Mode**

The D7000 series modules can transmit data values to the cloud IOT service Thingspeak.com. Analog and digital data values can be uploaded on a timed interval and stored on the Thingspeak servers. Data values can be retrieved, or downloaded, at a later time. The data values can be displayed using Thingspeak trend graphs or viewed from other IOT dashboard applications or websites.

### Modbus TCP/IP Protocol

The D7000 series modules utilize the Modbus TCP/IP protocol for communications. The Modbus TCP/IP protocol is widely supported protocol supported by almost all commercial data acquisition programs and programmable controllers in the marketplace. This allows for easy connection of a D7000 series module to an existing system or new application.

The D7000 series modules utilize up to eight different functions from within the Modbus TCP/IP protocol. The number of functions utilized by a module depends on the model type and the features it contains.

The Modbus functions allow users to control every function within a module. The functions and their descriptions are listed below. Each function is also outlined in further detail below.

Function	Description
01	Return coil status of discrete output points
02	Read ON/OFF status of discrete inputs in the slave device
03	Read content of holding registers (4X references) in the slave device
04	Read content of input registers (3X references) in the slave device
05	Force state of a single coil (digital output) to either ON or OFF
06	Preset the state of a single register to a specific value
0F	Force the state of a sequence of coils (digital outputs) to a specific state
10	Preset a sequence of registers (4X references) to specific values

Each Modbus TCP/IP message begins with a six byte preamble. The first two bytes of the preamble make up the "Transaction Identifier" and both bytes are typically "0". The second two bytes make up the "Protocol Identifier" and both bytes are typically "0". The last two bytes of the preamble contain the length of the message. The high byte of the message length is "0" and the low byte contains the number of bytes that follow the preamble.

All Modbus TCP/IP messages, commands and responses, contain a preamble as outlined above. The preamble values have been left out of the Modbus Function examples below.

### Function 01 - Read Coil Status

This function returns the coil status of discrete digital output points. A typical function 01 command and response is detailed below:

### **Command Usage:**

Address One Byte Slave Address Function One Byte Function Number

Addr HI Starting Address HI Byte Addr LO Starting Address LO Byte

Data HI Typically ZERO

Data LO Number of bits, limited to 1..64

### Response Message:

Address One Byte Slave Address Function One Byte Function Number

Data HI Data Coils (27-20)
Data LO Data Coils (35-28)

Data HI Data Coils (43-36)
Data LO Data Coils (51-44)

### Function 02 - Read Input Status

Read the ON/OFF status of discrete digital input bits in the slave device. A typical function 02 command and response is detailed below:

### **Command Usage:**

Address One Byte Slave Address Function One Byte Function Number

Addr HI Starting Address HI Byte Addr LO Starting Address LO Byte

Data HI Typically ZERO

Data LO Number of bits, limited to 1..64

### Response Message:

Address One Byte Slave Address Function One Byte Function Number

Data HI Data Coils (27-20)
Data LO Data Coils (35-28)

Data HI Data Coils (43-36)
Data LO Data Coils (51-44)

### Function 03 - Read Holding Registers

This function returns the contents of hold registers (4X references) in the slave device. A typical function 03 command and response is detailed below:

### **Command Usage:**

Address One Byte Slave Address Function One Byte Function Number

Addr HI Starting Register Address HI Byte
Addr LO Starting Register Address LO Byte

Data HI Typically ZERO
Data LO Number of registers

### Response Message:

Address One Byte Slave Address Function One Byte Function Number

Data HI HI Byte (8-bits)
Data LO LO Byte (8-bits)

### Function 04 - Read Input Registers

This function returns the contents of hold registers (3X references) in the slave device. A typical function 04 command and response is detailed below:

### **Command Usage:**

Address One Byte Slave Address Function One Byte Function Number

Addr HI Starting Register Address HI Byte
Addr LO Starting Register Address LO Byte

Data HI Typically ZERO
Data LO Number of registers

### Response Message:

Address One Byte Slave Address Function One Byte Function Number

Data HI HI Byte (8-bits)
Data LO LO Byte (8-bits)

### Function 05 - Force Single Coil

This function forces the state of a single coil (digital output) to either the ON or OFF state. A typical function 05 command and response is listed below:

### **Command Usage:**

Address One Byte Slave Address Function One Byte Function Number

Addr HI Coil Address HI Byte Addr LO Coil Address LO Byte

Data HI Force Data HI
Data LO Force Data LO

Data Values: The proper values are either 0xFF00 to enable (Turn ON) a bit or 0x0000

to disable (turn off) a bit.

### Response Message:

Address One Byte Slave Address
Function One Byte Function Number

Addr HI Coil Address HI Byte Same value as in command above.
Addr LO Same value as in command above.

Data HI Force Data HI Same value as in command above.

Data LO Force Data LO Same value as in command above.

### Function 06 - Preset Single Register

This function presets the state of a single register to a specific value. A typical function 06 command and response is listed below:

### **Command Usage:**

Address One Byte Slave Address Function One Byte Function Number

Addr HI Starting Register Address HI Byte
Addr LO Starting Register Address LO Byte

Data HI Force Data HI
Data LO Force Data LO

### Response Message:

Address One Byte Slave Address Function One Byte Function Number

Addr HI Register Address HI Byte Same value as in command above.

Addr LO Register Address LO Byte Same value as in command above.

Data HI Preset Data value HI Same value as in command above.
Data LO Preset Data value LO Same value as in command above.

### Function 0F - Force Multiple Coils

This function is used to force the state of multiple coils (digital outputs) in a digital output module. A typical function 0F command and response is listed below:

### **Command Usage:**

Address One Byte Slave Address Function One Byte Function Number

Starting Addr HI Starting Address HI Byte Starting Addr LO Starting Address LO Byte

Qty Coils HI Number of Coils to Write HI
Qty Coils LO Number of Coils to Write LO

Byte Count Number of Data Bytes Transmitted

Force Data HI
Force Data LO
Force Data LO

### Response Message:

Address One Byte Slave Address Function One Byte Function Number

Starting Addr HI Starting Address HI Byte Same value as in command above.

Starting Addr LO Starting Address LO Byte Same value as in command above.

Qty Coils HIQty Coils HISame value as in command above.Qty Coils LOSame value as in command above.

### Function 10 - Preset Multiple Registers

This function presets the state of multiple registers to specific values. A typical function 10 command and response is listed below:

### **Command Usage:**

Address One Byte Slave Address Function One Byte Function Number

Starting Addr HI Starting Register Address HI Byte Starting Addr LO Starting Register Address LO Byte

Num Registers HI Number of Registers to Write HI Num Registers LO Number of Registers to Write LO

Byte Count Number of Data Bytes Transmitted

Data HI Force Data HI
Data LO Force Data LO

### Response Message:

Address One Byte Slave Address Function One Byte Function Number

Starting Addr HI Starting Address HI Byte Same value as in command above. Starting Addr LO Starting Address LO Byte Same value as in command above.

Num Registers HI Preset Data value HI Same value as in command above.

Num Registers LO Preset Data value LO Same value as in command above.

### **Modbus Exceptions**

The following Modbus Exception (Error Codes) may be returned from the D7000 series modules. These Exception Codes are returned when an error is detected within the command messages transmitted to the module. All Exception Code numbers are indicated below with a detailed description of possible causes.

	Modbus Exception Codes					
Exception	Name	Description				
01	Illegal Function	This exception code is generated when the module does not recognize the function code.				
02	Illegal Data Address	This exception code is generated when the module does not support the specified data address in the command.				
03	Illegal Data Value	This exception code is generated if the command data is out of range for the function.				
06	Slave Busy	This exception code is generated during the first 3 seconds after the module is reset or powered up.				
07	Negative Acknowledge	This exception code is generated if the command tries to write a value into the module EEPROM without being write-enabled first.				

### **REST Protocol**

### 5.0 Modules and Register Maps

The D7000 series modules are a complete family of data acquisition modules. Mixing and matching the D7000 series modules together in an application provides any user with the ability to build a complete measurement and process control system. The family of modules includes multi-channel analog input modules, multiple channel analog output modules, and digital I/O modules.

#### **D7100 Voltage Input Module**

The <u>D7100</u> series analog input modules contain seven differential inputs for measuring DC voltages. Each input can be individually configured to measure one of six different voltage ranges. The input ranges are: +/-0.025V, +/-0.05V, +/-0.10V, +/-1V, +/-5V and +/-10V.

### **D7200 Current Input Module**

The <u>D7200</u> series analog input module contains seven differential inputs for measuring current signals such as 4-20mA loops. The analog input range is factory configured for +/-20mA.

#### **D7300 Thermocouple Input Module**

The <u>D7300</u> series analog input module contains seven differential inputs for measuring thermocouple probes. Each input can be individually configured to measure one of eight different thermocouple types. The supported thermocouple types are: J, K, T, E, R, S, B and C.

### D7400 Voltage, Thermocouple and Current Input Module

The <u>D7400</u> series analog input module contains seven differential inputs for measuring DC voltages, thermocouples and current. Each input can be individually configured to measure one of fourteen different ranges. The supported thermocouple types are: J, K, T, E, R, S, B and C. The DC voltage input ranges are: +/-0.025V, +/-0.05V, +/-0.10V, +/-1V, +/-5V and +/-10V and the current input range is +/-20mA.

#### **D7500 Analog Output Module**

The D7500 series analog output modules contain two analog output channels for generating either a voltage or current output signal. Each analog output channel contains two user-selectable voltage output ranges and two current output ranges. These analog output signals can be used as control inputs for items such as motor controls, valve controls, and other control devices. Each analog output channel also contains a programmable communications watchdog timer for instances when communications to the module is lost.

#### **D7700 Digital Inputs/Output Module**

The <u>D7710</u> series modules each contain 15-bits of digital inputs or digital outputs. The D7710 15-bit digital input module contains internal pull-ups on each bit for direct connection to dry contact switches.

The D7720 digital output modules contain fifteen open-collector outputs that can be connected up to 30Vdc and can sink 100mA per bit. The open-collector outputs allow the modules to be used in a wide variety of control applications. The digital output module also contains a programmable communications watchdog timer for accidental instances where communication to the module is lost.

The D7730 series digital input/output module contains seven digital inputs and eight open-collector digital outputs. The open-collector outputs can be used to control a wide variety of ON/OFF devices. The digital inputs contain internal pull-ups on each bit for direct connection to dry contact switches.

### 5.1 D7100 - Seven Channel Voltage Input Module

#### Overview

The D7100 series analog input modules contain seven differential analog inputs that can measure six different DC voltage ranges. Each analog input channel is user programmable and may be assigned to measure a different range. Any unused channels can be disabled.

#### **Analog to Digital Converter**

The D7100 series analog input modules contain a 16-bit analog to digital converter to perform the signal conversion to digital information. The analog to digital converter performs a total of 25 conversions per second. Meaning, if all 7 channels were enabled the each channel would be measured 3+ times per second. The conversion rate per channel can be improved by disabling any unused channels.

### **Features and Register Assignments**

The D7100 series analog input modules contain many user-selectable features. The user can select all features such as baud rate, parity type, analog range selection and digital filtering. The complete list of features is illustrated in the "Seven Analog Voltage Input Register Assignments" register map below. The register map format is used for consistency with the Modbus TCP/IP protocol. The register map contains the register numbers in decimal format, register description, acceptable data values, and list of what each value means. These registers can be written to using most any Modbus master program or using the DGH D7000 series utility software.

Note: All Modbus Register values in the tables below are represented as "decimal" numbers.

#### **Factory Initial Values**

The D7100 series analog module features are initialized at the factory with a set of "Initial Values". A complete list of factory "Initial Values" can be found in the table below

#### Calibration

The D7100 series analog input modules are shipped from the factory as fully calibrated devices. Throughout the lifetime of the module there may be need to verify or adjust the calibration of the device. The verification and adjustment process should only be completed using NIST traceable calibration equipment. A D7100 series Calibration procedure is included below.

#### **Connector Pin Designations**

The D7100 series module uses two 3.81mm removable plugs for connecting signals to the module. One two-pin connector is for the power supply connections. A second sixteen-pin connector is used to connect analog input signals to the module. The <u>pin designations</u> for each connector are printed on the module label and are listed in a table below.

### 5.1.2 Seven Voltage Input Pin Assignments and Specifications

### Connections Specifications

Power & Serial Communications	Analog Inputs	7 Channels

Pin Number	<u>Pin</u>	<u>Designator</u>	User Selectable Inp	out Ranges
1	GND	- Power Supply	Bipolar Voltage	10V, 5V, 1V,
2	+VS	+ Power Supply		0.1V, 0.05V,
		,		0.025V

**Differential Reading** 

### **Analog Input Pin Assignments**

			CH to CH	
Pin Number	<u>Pin</u>	<u>Designator</u>		
1	CH1+	CH1 +Input	Protocol	
2	CH1-	CH1 -Input	TCP	Modbus TCP/IP
3	CH2+	CH2 +Input	101	111000000 1 01 711
4	CH2-	CH2 -Input	Power Supply	
5	CH3+	CH3 +Input	Voltage	+10-30Vdc
6	CH3-	CH3 -Input	Power	1.4W
7	CH4+	CH4 +Input	1 OWCI	1.77
8	CH4-	CH4 -Input	Connectors	
9	CH5+	CH5 +Input	Spacing	3.81mm
10	CH5-	CH5 -Input	Max Wire Size	14-24 AWG
11	CH6+	CH6 +Input	Max Current	8 Amperes
12	CH6-	CH6 -Input	Wax Garrent	o 7 timporos
13	CH7+	CH7 +Input	Serial I ED Displays	
14	CH7-	CH7 -Input		TyData
15	ISO. GND	Isolated GND	` ',	
16	ISO. GND	Isolated GND	receive (Bottom)	Modu
13 14 15	CH7+ CH7- ISO. GND	CH6 -Input CH7 +Input CH7 -Input Isolated GND	Serial LED Displays Transmit (Top) Receive (Bottom)	TxData RxData

### 5.1.3 Seven Voltage Input Initial Values

Module Parameter	Value
Slave Address*	1
Baud Rate*	9600
Parity Type*	None
Modbus Response Delay	3mS
Modbus Query Delay	0mS
Conversion Rate	60Hz
Large Signal Filter	0 Seconds
Small Signal Filter	0 Seconds
Channel 0 Range	+/-10Vdc
Channel 1 Range	+/-10Vdc
Channel 2 Range	+/-10Vdc
Channel 3 Range	+/-10Vdc
Channel 4 Range	+/-10Vdc
Channel 5 Range	+/-10Vdc
Channel 6 Range	+/-10Vdc

<sup>\* =</sup> These values should not be changed.

## **5.1.4 Seven Voltage Input Register Assignments**

Register	<u>Description</u>	<u>Function</u>	<u>Value</u>	<u>Description</u>
40001	Slave Address	R/W	1-DF	Factory set to 0x0001.
40002	UART Setup	R/W		Factory set to 0x0035 = 9600, 8, N, 1.
40003	Modbus Delays	R/W	0-303F	Bits 0-7 The Response Delay in milliseconds. This is required when the RS-485 adapter cannot tri-state immediately after the last character is transmitted from the host. Maximum value is 63mS. Factory default value is 3.
				Bits 8-15 The End of Query Delay in milliseconds (48mS max). This is an additional time that the module will wait prior to marking the end of the message. Slower host computers may not be able transmit a continuous message stream, thereby creating gaps between characters exceeding the normal 3.5 character times limit. Factory default value is 0.  Factory set, 0x0003.
40033	Software Version	R		Factory set, Code Version.
40048	Last Converted Chan, Conversion Counter	R	0-06FF	Bits 0-7 The counter increments each conversion and rolled over after FF. The Conversion Counter indicates when the data registers have been updated.  Bits 8-10 Input channel last conversion stored. The information is useful when all channel data is read back with 1 query. The user can identify which channels have been converted since the last query as long as the time between queries is less than 8 conversion times.  Initialized to '0x0000' on device reset.
40049	Channel 0 Data	R	0-FFFF	Data - Ch 0, Offset binary, zero=0x8000.
40050	Channel 1 Data	R	0-FFFF	Data - Channel 1
40051	Channel 2 Data	R	0-FFFF	Data - Channel 2
40052	Channel 3 Data	R	0-FFFF	Data - Channel 3
40053	Channel 4 Data	R	0-FFFF	Data - Channel 4
40054	Channel 5 Data	R	0-FFFF	Data - Channel 5
40055	Channel 6 Data	R	0-FFFF	Data - Channel 6

40095	Misc. Setup	R/W	0-1	Bit 0 – Normal Mode Rejection Setting 0 – 60Hz, 25 Hz Conversion Speed. 1 – 50Hz, 20 Hz Conversion Speed. Factory set to 0x0000.
40096	Signal Filtering	R/W	0-3F	This register controls all channels. Time constants are only approximate values.  Bits 0-3 Small Filter Time Constant(Secs)  0 0 1 0.5 2 1 3 2 4 4 5 8 6 16 7 32  Bits 4-7 Large Filter Time Constant(Secs) 0 0
				1 0.5 2 1 3 2 4-7 Reserved Factory set to 0x0000.
40097	Setup Channel 0	R/W	0-F	Channel 0 range. Non-volatile write protected register. If the EEPROM cannot be written because of not being enabled, it replies with a Negative Acknowledge Exception response 07h. Modbus function code 10h is limited to 4 data values.    Range: Bits 0-7 Hex   00
40098	Setup Channel 1	R/W	0-F	Holds Channel 1 range.  Factory set to 0x0001.
40099	Setup Channel 2	R/W	0-F	Holds Channel 2 range.  Factory set to 0x0001.
40100	Setup Channel 3	R/W	0-F	Holds Channel 3 range.  Factory set to 0x0001.
40101	Setup Channel 4	R/W	0-F	Holds Channel 4 range.  Factory set to 0x0001.
40102	Setup Channel 5	R/W	0-F	Holds Channel 5 range. Factory set to 0x0001.
40103	Setup Channel 6	R/W	0-F	Holds Channel 6 range. Factory set to 0x0001.
40114	Trim Zero, 10V Range	WP	0	Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all channels. Calibration Acknowledge Exception Response. Calibration takes 20 seconds.
40115	Trim Zero, 5V Range	WP	0	Refer to Modbus register 40114.
40116	Trim Zero, 1V Range	WP	0	Refer to Modbus register 40114.

40117	Trim Zero, 0.1V Range	WP	0	Refer to Modbus register 40114. Apply calibration signal at least 1 minute prior to calibrating to all channels.
40118	Trim Zero, 0.05V Range	WP	0	Refer to Modbus register 40114. Apply calibration signal at least 1 minute prior to calibrating to all channels.
40119	Trim Zero, 0.025V Range	WP	0	Refer to Modbus register 40114. Apply calibration signal at least 1 minute prior to calibrating to all channels.
40146	Trim FS, 10V Range	WP	D000- FFFE	Forces all Channel Data Registers to written value, with appropriate input signal. Apply calibration signal at least 15 seconds prior to calibrating to all channels. Acknowledge Exception Response. Calibration takes 20 seconds. See note 1.
40147	Trim FS, 5V Range	WP	D000- FFFE	See Modbus Register 40146.
40148	Trim FS, 1V Range	WP	D000- FFFE	See Modbus Register 40146.
40149	Trim FS, 0.1V Range	WP	D000- FFFE	See Modbus Register 40146. Apply calibration signal at least 1 minute prior to calibrating to all channels.
40150	Trim FS, 0.05V Range	WP	D000- FFFE	See Modbus Register 40146. Apply calibration signal at least 1 minute prior to calibrating to all channels.
40151	Trim FS, 0.025V Range	WP	D000- FFFE	See Modbus Register 40146. Apply calibration signal at least 1 minute prior to calibrating to all channels.
40241	Control Register	W		<ul> <li>0 – Normal operation (NOP)</li> <li>1 – Remote Reset (write protected)</li> <li>2 – Write Enable</li> <li>5 – Initialize Host Communication setup</li> </ul>

Functions:

R Read Only
R/W Read/Write Write-Protected WP

### 5.1.5 Seven Channel Voltage Input Module Calibration Procedure

#### **Required Equipment:**

- 1. Computer running the DGH Utility Software or another Modbus Master program.
- 2. A NIST traceable DC Voltage Standard with +/-10Vdc range.

#### **Setup Steps – Perform Calibration Steps in Order Listed:**

- 1. Allow unit to warm up for 15 minutes.
- 2. Short all the +Input pins together using short jumper wires.
- 3. Short all the -Input pins together using short jumper wires.
- 4. Connect the +Input wires to the Positive terminal on the DC voltage calibrator.
- 5. Connect the -Input wires to the Negative terminal on the DC voltage calibrator.
- 6. Install the DGH Utility Software or another Modbus Master Program to communicate with, and calibrate with the module via serial port or a TCP/IP connection.

#### Trim Zero:

- 1. Set the DC calibrator voltage output to +0.0000Vdc.
- 2. Use the DGH Utility Software or a Modbus Master program to perform steps #3 & #5.
- 3. Set all channels to the same range. Start with +/-10Vdc range, work downward as per values in Table 1.0.
- 4. Trim Zero on all channels.
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Retrieve Trim Zero register value for specific range from Table 2.0 below.
  - c. Write value of 0x00h to Range Trim Zero register, (ie. 40114 for +/-10V).
  - d. Perform steps #4a through #4c to trim zero on each range.

### Trim Span:

- 1. Set the DC calibrator voltage output to +10.000Vdc.
- 2. Use the DGH Utility Software or a Modbus Master program to perform steps #3 & #5.
- 3. Set all channels to the same range. Start with +/-0.025Vdc range, work upward as per values in Table 3.0.
- 4. Trim Span on each channel.
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Retrieve Trim Span register value for specific range from Table 2.0 below.
  - c. Write value of 0xfffe to Trim Span register, (ie. 40146 for +/-10V).
  - d. Perform steps #4a through #4c to trim span on each range.

## **5.1.6 Seven Channel Voltage Input Calibration Tables:**

Seven Channel Range Register Values								
Channel Range Control Range Values								
Channel 0	40097	00	Disabled					
Channel 1	40098	01	+/-10V					
Channel 2	40099	02	+/-5V					
Channel 3	40100	03	+/-1V					
Channel 4	40101	04	+/-0.1V					
Channel 5	40102	05	+/-0.05V					
Channel 6	40103	06	+/-0.025V					

Table 1.0 Register Setup Values.

Trim Zero Registers and Calibration Values			
Range	Register	Value	
+/-10Vdc	40114	0000	
+/-5Vdc	40115	0000	
+/-1Vdc	40116	0000	
+/-0.1Vdc	40117	0000	
+/-0.05Vdc	40118	0000	
+/-0.025Vdc	40119	0000	

Table 2.0 Trim Zero Registers and Values.

Trim Span Registers and Calibration Values			
Range	Register	Value	
+/-0.025Vdc	40151	FFFE	
+/-0.05Vdc	40150	FFFE	
+/-0.1Vdc	40149	FFFE	
+/-1Vdc	40148	FFFE	
+/-5Vdc	40147	FFFE	
+/-10Vdc	40146	FFFE	

Table 3.0 Trim Span Registers and Values.

### 5.2 D7200 - Seven Channel Current Input Module

#### Overview

The D7200 series analog input module contains seven differential analog inputs for measuring current signals such as 4-20mA loops. Each analog input channel can measure current signals up to +/-20mA. Any unused channels can be disabled.

### **Analog to Digital Converter**

The D7200 series analog input modules contain a 16-bit analog to digital converter to perform the signal conversion to digital information. The analog to digital converter performs a total of 25 conversions per second. Meaning, if all 7 channels were enabled the each channel would be measured 3+ times per second. The conversion rate per channel can be improved by disabling any unused channels.

### **Features and Register Assignments**

The D7200 series analog input modules contain many user-selectable features. The user can select all features such as baud rate, parity type, analog range selection and digital filtering. The complete list of features is illustrated in the "Seven Channel Analog Current Input Register Assignments" register map below. The register map format is used for consistency with the Modbus RTU protocol. The register map contains the register numbers in decimal format, register description, acceptable data values, and list of what each value means. These registers can be written to using most any Modbus master program or using the DGH D6000 series utility software.

Note: All Modbus Register values in the tables below are represented as "decimal" numbers.

### **Factory Initial Values**

The D7200 series analog module features are initialized at the factory with a set of "Initial Values". A complete list of factory "Initial Values" can be found in the table below.

### Calibration

The D7200 series analog input modules are shipped from the factory as fully calibrated devices. Throughout the lifetime of the module there may be need to verify or adjust the calibration of the device. The verification and adjustment process should only be completed using NIST traceable calibration equipment. A D7200 series <u>Calibration procedure</u> is included below.

#### **Connector Pin Designations**

The D7200 series module uses two 3.81mm removable plugs for connecting signals to the module. One two-pin connector is for the power supply connections. A second sixteen-pin connector is used to connect analog input signals to the module. The <u>pin designations</u> for each connector are printed on the module label and are listed in a table below.

### **5.2.2 Seven Channel Current Input Specifications**

### Connections

### **Power & Serial Communications**

Pin Number	<u>Pin</u>	<u>Designator</u>
1	GND	- Power Supply
2	+VS	+ Power Supply

### **Analog Input Pin Assignments**

Pin Number	<u>Pin</u>	<u>Designator</u>
1	CH1+	CH1 +Input
2	CH1-	CH1 -Input
3	CH2+	CH2 +Input
4	CH2-	CH2 -Input
5	CH3+	CH3 +Input
6	CH3-	CH3 -Input
7	CH4+	CH4 +Input
8	CH4-	CH4 -Input
9	CH5+	CH5 +Input
10	CH5-	CH5 -Input
11	CH6+	CH6 +Input
12	CH6-	CH6 -Input
13	CH7+	CH7 +Input
14	CH7-	CH7 -Input
15	ISO. GND	Isolated GND
16	ISO. GND	Isolated GND

### **Specifications**

Analog	Inputs	7 Channels
, widiog	IIIPato	7 Ondinion

Input Range

Current +/-20mA

Differential Reading

CH to CH +/-10Vdc

Protocol

TCP Modbus TCP/IP

Power Supply

Voltage +10-30Vdc Power 1.4W

Connectors

Spacing 3.81mm
Max Wire Size 14-24 AWG
Max Current 8 Amperes

Serial LED Displays

Transmit (Top) TxData Receive (Bottom) RxData

### **5.2.3 Seven Channel Current Input Module Initial Values**

Module Parameter	Value
Slave Address*	1
Baud Rate*	9600
Parity Type*	None
Modbus Response Delay	3mS
Modbus Query Delay	0mS
Conversion Rate	60Hz
Large Signal Filter	0 Seconds
Small Signal Filter	0 Seconds
Channel 0 Range	+/-20mA
Channel 1 Range	+/-20mA
Channel 2 Range	+/-20mA
Channel 3 Range	+/-20mA
Channel 4 Range	+/-20mA
Channel 5 Range	+/-20mA
Channel 6 Range	+/-20mA

<sup>\* =</sup> These values should not be changed.

## **5.2.4 Seven Channel Current Input Register Assignments**

Register	<u>Description</u>	<u>Functions</u>	<u>Value</u>	<u>Description</u>
40001	Slave Address	R/W	1-DF	Factory set to 0x0001.
40002	UART Setup	R/W		Factory set to 0x0035 = 9600, 8, N, 1.
40003	Modbus Delays	R/W	0-303F	Bits 0-7 The Response Delay in milliseconds. This is required when the RS-485 adapter cannot tri-state immediately after the last character is transmitted from the host. Maximum value is 63mS. Factory default value is 3.
				Bits 8-15 The End of Query Delay in milliseconds (48mS max). This is an additional time that the module will wait prior to marking the end of the message. Slower host computers may not be able transmit a continuous message stream, thereby creating gaps between characters exceeding the normal 3.5 character times limit. Factory default value is 0.  Factory set, 0x0003.
40033	Software Version	R		Factory set, Code Version.
40048	Last Converted Chan, Conversion Counter	R	0-06FF	Bits 0-7 The counter increments each conversion and rolled over after FF. The Conversion Counter indicates when the data registers have been updated.  Bits 8-10 Input channel last conversion stored. The information is useful when all channel data is read back with 1 query. The user can identify which channels have been converted since the last query as long as the time between queries is less than 8 conversion times.  Initialized to '0x0000' on device reset.
40049	Channel 0 Data	R	0-FFFF	Data - Ch 0, Offset binary, zero=0x8000.
40050	Channel 1 Data	R	0-FFFF	Data - Channel 1
40051	Channel 2 Data	R	0-FFFF	Data - Channel 2
40052	Channel 3 Data	R	0-FFFF	Data - Channel 3
40053	Channel 4 Data	R	0-FFFF	Data - Channel 4
40054	Channel 5 Data	R	0-FFFF	Data - Channel 5
40055	Channel 6 Data	R	0-FFFF	Data - Channel 6

40095	Misc. Setup	R/W	0-1	Bit 0 – Normal Mode Rejection Setting 0 – 60Hz, 25 Hz Conversion Speed. 1 – 50Hz, 20 Hz Conversion Speed. Factory set to 0x0000.
40096	Signal Filtering	R/W	0-3F	This register controls all channels. Time constants are only approximate values.  Bits 0-3   Small Filter Time Constant(Secs)  1
40097	Setup Channel 0	R/W	0-F	Channel 0 range. Non-volatile write protected register. If the EEPROM cannot be written because of not being enabled, it replies with a Negative Acknowledge Exception response 07h. Modbus function code 10h is limited to 4 data values.    Range: Bits 0-7 Hex   Disable Channel   00
40098	Setup Channel 1	R/W	0-F	Holds Channel 1 range. Factory set to 0x0003.
40099	Setup Channel 2	R/W	0-F	Holds Channel 2 range. Factory set to 0x0003.
40100	Setup Channel 3	R/W	0-F	Holds Channel 3 range. Factory set to 0x0003.
40101	Setup Channel 4	R/W	0-F	Holds Channel 4 range. Factory set to 0x0003.
40102	Setup Channel 5	R/W	0-F	Holds Channel 5 range. Factory set to 0x0003.
40103	Setup Channel 6	R/W	0-F	Holds Channel 6 range. Factory set to 0x0003.
40116	Trim Zero, +/-20mA Range	WP	0	Force all channel data to 0x8000, input signal = 0. Wait 15 Secs, Write 0x0000.
40148	Trim FS, +/-20mA Range	WP	D000- FFFE	Force all channel data to top of range, Wait 15 Sec, Write value (0xfffe if +F.S.).
40241	Control Register	W		<ul> <li>0 – Normal operation (NOP)</li> <li>1 – Remote Reset (write protected)</li> <li>2 – Write Enable</li> <li>5 – Initialize Host Communication setup</li> </ul>

Functions: Read Only Read/Write R/W

WP Write-Protected

### 5.2.5 Seven Channel Current Input Calibration Procedure

### Required Equipment:

- 1. Computer running the DGH Utility Software or another Modbus Master program.
- 2. A NIST traceable DC Current Standard with +/-20mA range.

### **Setup Steps – Perform Calibration Steps in Order Listed:**

- 1. Allow unit to warm up for 15 minutes.
- 2. Connect the positive lead of DC current calibrator to Ch1 +Input terminal.
- 3. Connect the Ch1 –Input terminal the Ch2 +Input terminal.
- 4. Connect the Ch2 –Input terminal the Ch3 +Input terminal.
- 5. Connect the Ch3 –Input terminal the Ch4 +Input terminal.
- 6. Connect the Ch4 –Input terminal the Ch5 +Input terminal.
- 7. Connect the Ch5 –Input terminal the Ch6 +Input terminal.
- 8. Connect the Ch6 –Input terminal the Ch7 +Input terminal.
- 9. Connect the negative lead of the DC current calibrator to Ch7 –Input terminal.
- 10. Install the DGH Utility Software or another Modbus Master Program to communicate with, and calibrate with the module via serial port or a TCP/IP connection.
- 11. Using the DGH Utility Software configure all channels for the +/-20mA range using the data values in Table 1.0 below.

### Trim Zero:

- 1. Set the DC calibrator current output to +0.00mA. Wait 30 seconds.
- 2. Trim Zero on all channels.
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Trim Zero on all seven channels by writing a value of 0x0000h to Trim Zero register 40116. See Table 2.0 below.

### Trim Span:

- 1. Set the DC calibrator current output to +20.000mA. Wait 30 seconds.
- 2. Trim Span on all channels.
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Trim Span on all seven channels by writing a value of 0xfffe to Trim Span register 40148. See Table 3.0 below.

### **5.2.6 Seven Channel Current Input Calibration Tables:**

Seven Channel Current Register Values				
Channel	Range Control	Range Values		
Channel 0	40097	0 = Disabled		
Channel 1	40098	3 = +/-20mA		
Channel 2	40099			
Channel 3	40100			
Channel 4	40101			
Channel 5	40102			
Channel 6	40103			

Table 1.0 Register Setup Values.

Trim Zero Register and Calibration Value					
<u>Range</u>	Register <u>Value</u>				
+/-20mA	+/-20mA 40116 0000				

Table 2.0 Trim Zero Register and Value.

Trim Span Register and Calibration Value						
<u>Range</u>	Register <u>Value</u>					
+/-20mA	+/-20mA 40148 FFFE					

 Table 3.0 Trim Span Register and Value.

### 5.3 D7300 - Seven Channel Thermocouple Input Module

#### Overview

The D7300 series analog input module contains seven differential inputs for measuring thermocouple signals. Each analog input channel is user programmable and may be assigned to measure one of 8 different thermocouple types. The D7300 can measure thermocouple types J, K, T, E, R, S, B and C. Any unused channels can be disabled.

### **Analog to Digital Converter**

The D7300 series analog input modules contain a 16-bit analog to digital converter to perform the signal conversion to digital information. The analog to digital converter performs a total of 25 conversions per second. Meaning, if all 7 channels were enabled the each channel would be measured 3+ times per second. The conversion rate per channel can be improved by disabling any unused channels.

### **Features and Register Assignments**

The D7300 series analog input modules contain many user-selectable features. The user can select all features such as baud rate, parity type, analog range selection and digital filtering. The complete list of features is illustrated in the "Seven Channel Analog Thermocouple Input Register Assignments" register map below. The register map format is used for consistency with the Modbus RTU protocol. The register map contains the register numbers in decimal format, register description, acceptable data values, and list of what each value means. These registers can be written to using most any Modbus master program or using the DGH D6000 series utility software.

Note: All Modbus Register values in the tables below are represented as "decimal" numbers.

### **Factory Initial Values**

The D7300 series analog module features are initialized at the factory with a set of "Initial Values". A complete list of factory "Initial Values" can be found in the table below.

### Calibration

The D7300 series analog input modules are shipped from the factory as fully calibrated devices. Throughout the lifetime of the module there may be need to verify or adjust the calibration of the device. The verification and adjustment process should only be completed using NIST traceable calibration equipment. A D7300 series <u>Calibration procedure</u> is included below.

### **Connector Pin Designations**

The D7300 series module uses two 3.81mm removable plugs for connecting signals to the module. One two-pin connector is for the power supply connections. A second sixteen-pin connector is used to connect analog input signals to the module. The <u>pin designations</u> for each connector are printed on the module label and are listed in a table below.

### 5.3.2 Seven Channel Thermocouple Input Specifications

### Connections Specifications

### **Power & Serial Communications**

# Pin NumberPinDesignator1GND- Power Supply2+VS+ Power Supply

## Thermocouple

Differential Reading
CH to CH +/-10Vdc

### **Analog Input Pin Assignments**

Pin Number	<u>Pin</u>	<u>Designator</u>
1	CH1+	CH1 +Input
2	CH1-	CH1 -Input
3	CH2+	CH2 +Input
4	CH2-	CH2 -Input
5	CH3+	CH3 +Input
6	CH3-	CH3 -Input
7	CH4+	CH4 +Input
8	CH4-	CH4 -Input
9	CH5+	CH5 +Input
10	CH5-	CH5 -Input
11	CH6+	CH6 +Input
12	CH6-	CH6 -Input
13	CH7+	CH7 +Input
14	CH7-	CH7 -Input
15	ISO. GND	Isolated GND
16	ISO. GND	Isolated GND

## Protocol

TCP Modbus TCP/IP

7 Channels

J,K,T,E,R,S,B,C

# Power Supply Voltage

Analog Inputs

Input Type

Voltage +10-30Vdc Power 1.4W

### Connectors

Spacing 3.81mm
Max Wire Size 14-24 AWG
Max Current 8 Amperes

### Serial LED Displays

Transmit (Top) TxData Receive (Bottom) RxData

### **5.3.3 Seven Channel Thermocouple Input Module Initial Values**

Module Parameter	Value
Slave Address*	1
Baud Rate*	9600
Parity Type*	None
Modbus Response Delay	3mS
Modbus Query Delay	0mS
Conversion Rate	60Hz
Large Signal Filter	0 Seconds
Small Signal Filter	0 Seconds
Channel 0 Range	J-Tc Type
Channel 1 Range	J-Tc Type
Channel 2 Range	J-Tc Type
Channel 3 Range	J-Tc Type
Channel 4 Range	J-Tc Type
Channel 5 Range	J-Tc Type
Channel 6 Range	J-Tc Type

<sup>\* =</sup> These values should not be changed.

### 5.3.4 Seven Channel Thermocouple Input Register Assignments

Register	<u>Description</u>	Functions	<u>Value</u>	<u>Description</u>
40001	Slave Address	R/W	1-DF	Factory set to 0x0001.
40002	UART Setup	R/W		Factory set to 0x0035 = 9600, 8, N, 1.
40003	Modbus Delays	R/W	0-303F	Bits 0-7 The Response Delay in milliseconds. This is required when the RS-485 adapter cannot tri-state immediately after the last character is transmitted from the host. Maximum value is 63mS. Factory default value is 3.
				Bits 8-15 The End of Query Delay in milliseconds (48mS max). This is an additional time that the module will wait prior to marking the end of the message. Slower host computers may not be able transmit a continuous message stream, thereby creating gaps between characters exceeding the normal 3.5 character times limit. Factory default value is 0.  Factory set, 0x0003.
40033	Software Version	R		Factory set, Code Version.
40048	Last Converted Chan, Conversion Counter	R	0-06FF	Bits 0-7 The counter increments each conversion and rolled over after FF. The Conversion Counter indicates when the data registers have been updated.  Bits 8-10 Input channel last conversion stored. The information is useful when all channel data is read back with 1 query. The user can identify which channels have been converted since the last query as long as the time between queries is less than 8 conversion times.  Initialized to '0x0000' on device reset.
40049	Channel 0 Data	R	0-FFFF	Data - Ch 0, Offset binary, zero=0x8000.
40050	Channel 1 Data	R	0-FFFF	Data - Channel 1
40051	Channel 2 Data	R	0-FFFF	Data - Channel 2
40052	Channel 3 Data	R	0-FFFF	Data - Channel 3
40053	Channel 4 Data	R	0-FFFF	Data - Channel 4
40054	Channel 5 Data	R	0-FFFF	Data - Channel 5
40055	Channel 6 Data	R	0-FFFF	Data - Channel 6

40095	Misc. Setup	R/W	0-1	Bit 0 – Normal Mode Rejection Setting 0 – 60Hz, 25 Hz Conversion Speed. 1 – 50Hz, 20 Hz Conversion Speed. Factory set to 0x0000.
40096	Signal Filtering	R/W	0-3F	This register controls all channels. Time constants are only approximate values.  Bits 0-3
40097	Setup Channel 0	R/W	0-F	Factory set to 0x0000.  Channel 0 range. Non-volatile write protected register. If the EEPROM cannot be written because of not being enabled, it replies with a Negative Acknowledge Exception response 07h. Modbus function code 10h is limited to 4 data values.
				Range:         Bits 0-7 Hex           Disable Channel         00           J-Tc (-200-760C)         21           K-Tc (-150-1250C)         22           T-Tc (-200-400C)         23           E-Tc (-100-1000C)         24           R-Tc (+0-1750C)         25           S-Tc (+0-1750C)         26           B-Tc (+0-1820C)         27           C-Tc (+0-2315C)         28           Factory set to 0x0003.
40098	Setup Channel 1	R/W	0-F	Holds Channel 1 range.  Factory set to 0x0003.
40099	Setup Channel 2	R/W	0-F	Holds Channel 2 range. Factory set to 0x0003.
40100	Setup Channel 3	R/W	0-F	Holds Channel 3 range. Factory set to 0x0003.
40101	Setup Channel 4	R/W	0-F	Holds Channel 4 range. Factory set to 0x0003.
40102	Setup Channel 5	R/W	0-F	Holds Channel 5 range. Factory set to 0x0003.
40103	Setup Channel 6	R/W	0-F	Holds Channel 6 range. Factory set to 0x0003.
40116	Trim Zero, +/-20mA Range	WP	0	Force all channel data to 0x8000, input signal = 0. Wait 15 Secs, Write 0x0000.
40148	Trim FS, +/-20mA Range	WP	D000- FFFE	Force all channel data to top of range, Wait 15 Sec, Write value (0xfffe if +F.S.).
40241	Control Register	W		0 – Normal operation (NOP) 1 – Remote Reset (write protected) 2 – Write Enable 5 – Initialize Host Communication setup

### 5.3.5 Seven Channel Thermocouple Input Calibration Procedure

### Required Equipment:

- 1. Computer running the DGH Utility Software or another Modbus Master program.
- 2. A NIST traceable DC Voltage Standard.

### **Setup Steps – Perform Calibration Steps in Order Listed:**

- 1. Allow unit to warm up for 15 minutes.
- 2. Connect the positive lead of DC current calibrator to Ch1 +Input terminal.
- 3. Connect the Ch1 –Input terminal the Ch2 +Input terminal.
- 4. Connect the Ch2 –Input terminal the Ch3 +Input terminal.
- 5. Connect the Ch3 –Input terminal the Ch4 +Input terminal.
- 6. Connect the Ch4 –Input terminal the Ch5 +Input terminal.
- 7. Connect the Ch5 –Input terminal the Ch6+Input terminal.
- 8. Connect the Ch6 –Input terminal the Ch7 +Input terminal.
- 9. Connect the negative lead of the DC current calibrator to Ch7 –Input terminal.
- 10. Install the DGH Utility Software or another Modbus Master Program to communicate with, and calibrate with the module via serial port or a TCP/IP connection.
- 11. Using the DGH Utility Software configure all channels for the +/-20mA range using the data values in Table 1.0 below.

### Trim Zero:

- 1. Set the DC calibrator current output to +0.00mV. Wait 30 seconds.
- 2. Trim Zero on all channels.
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Trim Zero on all seven channels by writing a value of 0x0000h to Trim Zero register 40116. See Table 2.0 below.

### Trim Span:

- 1. Set the DC calibrator current output to +20.000mA. Wait 30 seconds.
- 2. Trim Span on all channels.
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Trim Span on all seven channels by writing a value of 0xfffe to Trim Span register 40148. See Table 3.0 below.

#### Trim CJC's:

- 1. Set the input signal to ----.
- 2. Set all module channels to the J-Thermocouple range.
- 3. Use the DGH Utility Software or a Modbus Master program to perform steps #4 & #5.
- 4. Trim Zero on each input channel
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Write a value of 0x0000h to register 40114.
- 5. Apply input signal to each channel from Table x.xx.
  - a. Wait 1 minute.
  - b. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - c. Write a value of 0xfffe

### **Trim Thermocouples:**

- 1. Set the input signal to ----.
- Set all module channels to the J-Thermocouple range.
   Use the DGH Utility Software or a Modbus Master program to perform steps #4 & #5.
- 4. Trim Zero on each input channel
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Write a value of 0x0000h to register 40114.
- 5. Apply input signal to each channel from Table x.xx.

  - a. Wait 1 minute.
    b. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - **c.** Write a value of 0xfffe

### **5.3.5 Seven Channel Thermocouple Input Calibration Tables:**

Seven Channel Range Register Values							
Channel	Range Control	Range Values					
Channel 0	40097	00	Disabled				
Channel 1	40098	04	+/-0.1V				
Channel 2	40099	05	+/-0.05V				
Channel 3	40100	06	+/-0.025V				
Channel 4	40101	21	J-Type TC				
Channel 5	40102	22	K-Type TC				
Channel 6	40103	23	T-Type TC				
J	.3100	24	E-Type TC				
		25	R-Type TC				
		26	S-Type TC				
		27	B-Type TC				
		28	C-Type TC				

Table 1.0 Register Setup Values.

Trim Zero Registers and Calibration Values						
Range	Register	<u>Value</u>				
+/-10Vdc	40114	0000				
+/-5Vdc	40115	0000				
+/-1Vdc	40116	0000				
+/-0.1Vdc	40117	0000				
+/-0.05Vdc	40118	0000				
+/-0.025Vdc	40119	0000				

Table 2.0 Trim Zero Registers and Values.

Trim Span Registers and Calibration Values						
Range	Register	Value				
+/-0.025Vdc	40151	FFFE				
+/-0.05Vdc	40150	FFFE				
+/-0.1Vdc	40149	FFFE				
+/-1Vdc	40148	FFFE				
+/-5Vdc	40147	FFFE				
+/-10Vdc	40146	FFFE				

Table 3.0 Trim Span Registers and Values.

CJC Calibration Registers and Values						
Channels	Register	Increase Value	Decrease Value			
03	40129	0001	0000			
46	40130	0001	0000			

Table 4.0 Trim CJC Registers and Values.

### 5.4 D7400 - Seven Channel Voltage, Thermocouple, Current Input Module

#### Overview

The D7400 series analog input module contains seven analog inputs for measuring voltages, thermocouples and current. Each analog input channel is user programmable and may be assigned to different input types.

When measuring voltages or thermocouples, simply use the Utility Software to select the type of signal and range. When configuring any channel to measure current loops or 4-20mA signals then the Input range can be set to either the +/-1Vdc or +/-20mA selections. The module uses the +/-1Vdc range to measure current up to 20mA.

When measuring current signals then a measurement sense resistor must be enabled via jumpers inside the module. Each channel has a jumper strip that must be shorted using a provided shorting bar to enable the sense resistor. The sense resistor is internally connected directly across the channel+ and channel- input pins. See the D7400 board layout below for instructions on taking the module and enabling the jumpers.

### **Analog to Digital Converter**

The D7400 series analog input modules contain a 16-bit analog to digital converter to perform the signal conversion to digital information. The analog to digital converter performs a total of 25 conversions per second. Meaning, if all 7 channels were enabled the each channel would be measured 3+ times per second. The conversion rate per channel can be improved by disabling any unused channels.

### **Features and Register Assignments**

The D7400 series analog input modules contain many user-selectable features. The user can select all features such as baud rate, parity type, analog range selection and digital filtering. The complete list of features is illustrated in the "Seven Channel Voltage, Thermocouple and Current Input Register Assignments" register map below. The register map format is used for consistency with the Modbus RTU protocol. The register map contains the register numbers in decimal format, register description, acceptable data values, and list of what each value means. These registers can be written to using most any Modbus master program or using the DGH D6000 series utility software.

Note: All Modbus Register values in the tables below are represented as "decimal" numbers.

#### **Factory Initial Values**

The D7400 series analog module features are initialized at the factory with a set of "Initial Values". A complete list of factory "Initial Values" can be found in the table below.

### Calibration

The D7400 series analog input modules are shipped from the factory as fully calibrated devices. Throughout the lifetime of the module there may be need to verify or adjust the calibration of the device. The verification and adjustment process should only be completed using NIST traceable calibration equipment. A D7400 series <u>Calibration procedure</u> is included below.

#### **Connector Pin Designations**

The D7400 series module uses two 3.81mm removable plugs for connecting signals to the module. One two-pin connector is for the power supply connections. A second sixteen-pin connector is used to connect analog input signals to the module. The <u>pin designations</u> for each connector are printed on the module label and are listed in a table below.

# **5.4.1 Seven Channel Voltage, Thermocouple, Current Input Pin Assignments and Specifications**

## Connections Specifications

			-	
Power & Serial	Communica	ations	Analog Inputs	7 Channels
Pin Number 1 2	<u>Pin</u> GND +VS	<u>Designator</u> - Power Supply + Power Supply	User Selectable Inpu Bipolar Voltage	t Ranges 10V, 5V, 1V, 0.1V, 0.05V, 0.025V
Analog Input Pi	n Assignme	ents	Thermocouple Current	J,K,T,E,R,S,B,C +/-20mA
Pin Number 1 2 3	<u>Pin</u> CH1+ CH1- CH2+	Designator CH1 +Input CH1 -Input CH2 +Input	Differential Reading CH to CH	
4 5	CH2- CH3+	CH2 -Input CH3 +Input	Protocol TCP	Modbus TCP/IP
6 7 8 9	CH3- CH4+ CH4- CH5+	CH3 -Input CH4 +Input CH4 -Input CH5 +Input	Power Supply Voltage Power	+10-30Vdc 1.4W
10 11 12 13 14	CH5- CH6+ CH6- CH7+ CH7-	CH5 -Input CH6 +Input CH6 -Input CH7 +Input CH7 -Input	Connectors Spacing Max Wire Size Max Current	3.81mm 14-24 AWG 8 Amperes
15 16	ISO. GND ISO. GND	Isolated GND Isolated GND	Serial LED Displays Transmit (Top)	TxData

Receive (Bottom)

**RxData** 

### 5.4.2 Seven Channel Voltage, Thermocouple and Current Input Initial Values

Module Parameter	Value
Slave Address	1
Baud Rate	9600
Parity Type	None
Modbus Response Delay	3mS
Modbus Query Delay	0mS
Conversion Rate	60Hz
Large Signal Filter	0 Seconds
Small Signal Filter	0 Seconds
Channel 1 Range	+/-10Vdc
Channel 2 Range	+/-10Vdc
Channel 3 Range	+/-10Vdc
Channel 4 Range	+/-10Vdc
Channel 5 Range	+/-10Vdc
Channel 6 Range	+/-10Vdc
Channel 7 Range	+/-10Vdc

## 5.4.3 Seven Channel Voltage, Thermocouple and Current Input Register Assignments

Register	<u>Description</u>	Functions	<u>Value</u>	<u>Description</u>
40001	Slave Address	R/W	1-DF	Factory set to 0x0001.
40002	UART Setup	R/W		Bits 0-4 Baud Rate
				5=9600
				6=19.2K
				7=38.4K
				8=57.6K
				9=115.2K
				Bits 5-6 Parity
				0=No Parity, 8-N-2
				1=Odd
				2=Even
				3=No Parity, 8-N-1
				Factory set to 0x0035 = 9600, 8, N, 1.
40003	Modbus Delays	R/W	0-303F	Bits 0-7
				The Response Delay in milliseconds. This is
				required when the RS-485 adapter cannot tri-state
				immediately after the last character is transmitted
				from the host. Maximum value is 63mS. Factory default value is 3.
				deladit value is 5.
				Bits 8-15
				The End of Query Delay in milliseconds (48mS
				max). This is an additional time that the module will
				wait prior to marking the end of the message.
				Slower host computers may not be able transmit a
				continuous message stream, thereby creating gaps
				between characters exceeding the normal 3.5
				character times limit. Factory default value is 0.
40000	0.6			Factory set, 0x0003.
40033	Software Version	R R	0.0655	Factory set, Code Version.
40048	Last Converted	K	0-06FF	Bits 0-7 The counter increments each conversion and rolled
	Chan, Conversion			over after FF. The Conversion Counter indicates
	Counter			when the data registers have been updated.
	Counter			Bits 8-10
				Input channel last conversion stored. The
				information is useful when all channel data is read
				back with 1 query. The user can identify which
				channels have been converted since the last query
				as long as the time between queries is less than 8
				conversion times.
100.00				Initialized to '0x0000' on device reset.
40049	Channel 1 Data	R	0-FFFF	Data - Ch 1, Offset binary, zero=0x8000.
40050	Channel 2 Data	R	0-FFFF	Data - Channel 2
40051	Channel 3 Data	R	0-FFFF	Data - Channel 3
40052	Channel 4 Data	R	0-FFFF	Data - Channel 4
40053	Channel 5 Data	R	0-FFFF	Data - Channel 5
40054 40055	Channel 6 Data Channel 7 Data	R R	0-FFFF 0-FFFF	Data - Channel 6 Data - Channel 7
40055	Channel / Data	K	U-FFFF	Data - Channel /

0 - 60Hz, 25 Hz Conversion Speed.   1 - 50Hz, 20 Hz Conversion Speed.   1 - 50Hz Conversion Spe	40005	Min Onton	D // //	0.4	D'( 0 N   1M   D   1   1   0   1   1	
1 - 50Hz, 20 Hz Conversion Speed.   Factory set to X0000.	40095	Misc. Setup	R/W	0-1		
Factory set to 0x0000.						
A0096   Signal Filtering   R/W   O-3F   This register controls all channels. Time constants are only approximate values.   Bits 0-3   Small Filter Time Constant(Secs)   0   1   0.5   2   4   4   4   5   8   6   6   16   7   32   8   8   6   16   7   32   9   1   10.5   2   1   1   10.5   2   1   1   10.5   2   1   1   10.5   2   1   1   10.5   2   1   1   10.5   2   1   1   1   10.5   2   1   1   1   1   1   1   1   1   1						
are only approximate values   Bits 0-3   Small Filter Time Constant(Secs)   3   0   1   0.5   2   1   3   2   4   4   4   5   8   6   16   7   32   32   4   4   7   8   8   6   16   7   32   8   8   6   16   7   32   8   8   6   16   7   32   8   8   6   16   7   32   8   8   7   8   8   8   8   8   8   8	40006	Cianal Filtorina	D/M	0.25		
Bits 0-3   Small Filter Time Constant(Secs)   3   1   0.5   2   1   1   0.5   2   1   3   3   2   4   4   4   4   5   8   6   16   7   32   8   1   0.5   2   2   1   3   3   2   2   4   4   4   5   8   6   16   7   32   8   1   1   0.5   2   2   1   3   2   2   4   7   Reserved   Factory set to 0x0000.   1   0.5   2   2   1   3   2   2   4   7   Reserved   Factory set to 0x0000.   1   0.5   2   2   1   3   2   2   4   7   Reserved   Factory set to 0x0000.   1   0.5   2   2   1   3   2   2   4   7   Reserved   Factory set to 0x0000.   1   0.5   2   2   1   3   2   2   1   3   2   2   4   7   Reserved   Factory set to 0x0000.   1   0.5   2   1   1   1   1   1   1   1   1   1	40096	Signal Fillering	R/VV	0-3F		
3						
1						
2						
3						
A						
Setup Channel 1						
Bits 4-7   Large Filter Time Constant(Secs)						
August   Bits 4-7   Large Filter Time Constant(Secs)   0   0   0   0   1   0.5   2   2   1   3   3   2   4-7   Reserved   Factory set to 0x0000.   Channel 1 range. Non-volatile write protected register. If the EEPROM cannot be written because of not being enabled, it replies with a Negative Acknowledge Exception response 07h. Modbus function code 10h is limited to 4 data values.   Range: Bits 0-7 Hex Disable Channel 00   H-100						
Bits 4-7   Large Filter Time Constant(Secs)						
0					7 32	
0					Dite 4.7	
1						
2 1 3 2 4-7 Reserved   Factory set to 0x0000.						
3 2   4-7   Reserved   Factory set to 0x0000.						
4-7 Reserved   Factory set to 0x0000.						
Factory set to 0x0000.   Channel 1 range. Nor-votatile write protected register. If the EEPROM cannot be written because of not being enabled, it replies with a Negative Acknowledge Exception response 07h. Modbus function code 10h is limited to 4 data values.   Range: Disable Channel						
Setup Channel 1   R/W   O-F   Channel 1 range. Non-volatile writer protected register. If the EEPROM cannot be written because of not being enabled, it replies with a Negative Acknowledge Exception response 07h. Modbus function code 10h is limited to 4 data values.    Range: Bits 0-7 Hex Disable Channel						
Register. If the EEPROM cannot be written because of not being enabled, it replies with a Negative Acknowledge Exception response 07h. Modbus function code 10h is limited to 4 data values.    Range:	40007	0-6	D // /	2 -		
Of not being enabled, it replies with a Negative Acknowledge Exception response 07h. Modbus function code 10h is limited to 4 data values.   Range: Bits 0-7 Hex Disable Channel 00	40097	Setup Channel 1	R/W	0-F		
Acknowledge Exception response 07h. Modbus function code 10h is limited to 4 data values.   Range:						
Range: Bits 0-7 Hex						
Range: Bits 0-7 Hex						
Disable Channel					function code 10h is limited to 4 data values.	
Disable Channel					D-11-10	
H/-10V						
+/-5V   02						
+/-1V						
+/-0.100V						
+/-0.050V   05						
+/-0.025V   06   J-Tc (-200-760C)   21   K-Tc (-150-1250C)   22   T-Tc (-200-400C)   23   E-Tc (-100-1000C)   24   R-Tc (+0-1750C)   25   S-Tc (+0-1750C)   25   S-Tc (+0-1750C)   26   B-Tc (+0-1820C)   27   C-Tc (+0-2315C)   28   +/-20mA Current   03 (Special)   Factory set to 0x0001.   40098   Setup Channel 2   R/W   0-F   Holds Channel 2 range.   Factory set to 0x0001.   40099   Setup Channel 3   R/W   0-F   Holds Channel 3 range.   Factory set to 0x0001.   40100   Setup Channel 4   R/W   0-F   Holds Channel 4 range.   Factory set to 0x0001.   40101   Setup Channel 5   R/W   0-F   Holds Channel 5 range.   Factory set to 0x0001.   40102   Setup Channel 6   R/W   0-F   Holds Channel 6 range.   Factory set to 0x0001.   40103   Setup Channel 7   R/W   0-F   Holds Channel 6 range.   Factory set to 0x0001.   40103   Setup Channel 7   R/W   0-F   Holds Channel 6 range.   Factory set to 0x0001.   40104   Trim Zero, 10V   Range   Factory set to 0x0001.   40105   Factory set to 0x0001.   40106   Trim Zero, 10V   Range   Factory set to 0x0001.   40106   Trim Zero, 10V   Range   Factory set to 0x0001.   40107   Trim Zero, 10V   Range   Factory set to 0x0001.   40108   Trim Zero, 10V   Range   Factory set to 0x0001.   40108   Trim Zero, 10V   Range   Factory set to 0x0001.   40108   Trim Zero, 10V   MP   0   Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all						
J-Tc (-200-760C)   21     K-Tc (-150-1250C)   22     T-Tc (-200-400C)   23     E-Tc (-100-1000C)   24     R-Tc (+0-1750C)   25     S-Tc (+0-1750C)   26     B-Tc (+0-1820C)   27     C-Tc (+0-2315C)   28     +/-20mA Current   03 (Special)     Factory set to 0x0001.     40098   Setup Channel 2   R/W   0-F   Holds Channel 2 range.     Factory set to 0x0001.     40100   Setup Channel 4   R/W   0-F   Holds Channel 3 range.     Factory set to 0x0001.     40101   Setup Channel 5   R/W   0-F   Holds Channel 4 range.     Factory set to 0x0001.     40102   Setup Channel 6   R/W   0-F   Holds Channel 5 range.     Factory set to 0x0001.     40103   Setup Channel 6   R/W   0-F   Holds Channel 6 range.     Factory set to 0x0001.     40104   Trim Zero, 10V   WP   0   Holds Channel 7 range.     Factory set to 0x0001.     40114   Trim Zero, 10V   WP   0   Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all						
K-Tc (-150-1250C)   22   T-Tc (-200-400C)   23   E-Tc (-100-1000C)   24   R-Tc (+0-1750C)   25   E-Tc (+0-1750C)   25   E-Tc (+0-1750C)   26   E-Tc (+0-1820C)   27   C-Tc (+0-2315C)   28   E-Tc (+0-1820C)   27   E-Tc (+0-1820C)						
T-Tc (-200-400C)   23     E-Tc (-100-1000C)   24     R-Tc (+0-1750C)   25     S-Tc (+0-1750C)   26     B-Tc (+0-1820C)   27     C-Tc (+0-2315C)   28     +/-20mA Current   03 (Special)     Factory set to 0x0001.     40098   Setup Channel 2   R/W   0-F   Holds Channel 2 range.     Factory set to 0x0001.     40099   Setup Channel 3   R/W   0-F   Holds Channel 3 range.     Factory set to 0x0001.     40100   Setup Channel 4   R/W   0-F   Holds Channel 4 range.     Factory set to 0x0001.     40101   Setup Channel 5   R/W   0-F   Holds Channel 5 range.     Factory set to 0x0001.     40102   Setup Channel 6   R/W   0-F   Holds Channel 6 range.     Factory set to 0x0001.     40103   Setup Channel 7   R/W   0-F   Holds Channel 6 range.     Factory set to 0x0001.     40104   Trim Zero, 10V   WP   0   Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all						
E-Tc (-100-1000C)					,	
R-Tc (+0-1750C)   25   S-Tc (+0-1750C)   26   B-Tc (+0-1820C)   27   C-Tc (+0-2315C)   28   +/-20mA Current   03 (Special)						
S-Tc (+0-1750C)   26     B-Tc (+0-1820C)   27     C-Tc (+0-2315C)   28     +/-20mA Current   03 (Special)     Factory set to 0x0001.     40098   Setup Channel 2   R/W   0-F   Holds Channel 2 range.     Factory set to 0x0001.     40099   Setup Channel 3   R/W   0-F   Holds Channel 3 range.     Factory set to 0x0001.     40100   Setup Channel 4   R/W   0-F   Holds Channel 4 range.     Factory set to 0x0001.     40101   Setup Channel 5   R/W   0-F   Holds Channel 5 range.     Factory set to 0x0001.     40102   Setup Channel 6   R/W   0-F   Holds Channel 6 range.     Factory set to 0x0001.     40103   Setup Channel 7   R/W   0-F   Holds Channel 7 range.     Factory set to 0x0001.     40104   Trim Zero, 10V   Range   Process all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all						
B-Tc (+0-1820C)   27   C-Tc (+0-2315C)   28   28   20   20   20   20   20   20						
C-Tc (+0-2315C) 28 +/-20mA Current 03 (Special) Factory set to 0x0001.  40098 Setup Channel 2 R/W 0-F Holds Channel 2 range. Factory set to 0x0001.  40099 Setup Channel 3 R/W 0-F Holds Channel 3 range. Factory set to 0x0001.  40100 Setup Channel 4 R/W 0-F Holds Channel 4 range. Factory set to 0x0001.  40101 Setup Channel 5 R/W 0-F Holds Channel 5 range. Factory set to 0x0001.  40102 Setup Channel 6 R/W 0-F Holds Channel 6 range. Factory set to 0x0001.  40103 Setup Channel 7 R/W 0-F Holds Channel 6 range. Factory set to 0x0001.  40104 Trim Zero, 10V Range Factory set to 0x0001.  40105 Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	1					
+/-20mA Current	1					
Factory set to 0x0001.  40098 Setup Channel 2 R/W 0-F Holds Channel 2 range. Factory set to 0x0001.  40099 Setup Channel 3 R/W 0-F Holds Channel 3 range. Factory set to 0x0001.  40100 Setup Channel 4 R/W 0-F Holds Channel 4 range. Factory set to 0x0001.  40101 Setup Channel 5 R/W 0-F Holds Channel 5 range. Factory set to 0x0001.  40102 Setup Channel 6 R/W 0-F Holds Channel 6 range. Factory set to 0x0001.  40103 Setup Channel 7 R/W 0-F Holds Channel 6 range. Factory set to 0x0001.  40104 Trim Zero, 10V WP 0 Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	1				,	
40098   Setup Channel 2   R/W   0-F   Holds Channel 2 range.   Factory set to 0x0001.     40099   Setup Channel 3   R/W   0-F   Holds Channel 3 range.   Factory set to 0x0001.     40100   Setup Channel 4   R/W   0-F   Holds Channel 4 range.   Factory set to 0x0001.     40101   Setup Channel 5   R/W   0-F   Holds Channel 5 range.   Factory set to 0x0001.     40102   Setup Channel 6   R/W   0-F   Holds Channel 6 range.   Factory set to 0x0001.     40103   Setup Channel 7   R/W   0-F   Holds Channel 7 range.   Factory set to 0x0001.     40114   Trim Zero, 10V   Range   WP   0   Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	1					
Factory set to 0x0001.  40099 Setup Channel 3 R/W 0-F Holds Channel 3 range. Factory set to 0x0001.  40100 Setup Channel 4 R/W 0-F Holds Channel 4 range. Factory set to 0x0001.  40101 Setup Channel 5 R/W 0-F Holds Channel 5 range. Factory set to 0x0001.  40102 Setup Channel 6 R/W 0-F Holds Channel 6 range. Factory set to 0x0001.  40103 Setup Channel 7 R/W 0-F Holds Channel 7 range. Factory set to 0x0001.  40104 Trim Zero, 10V WP 0 Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	40000	0-6	D // /			
40099   Setup Channel 3   R/W   0-F   Holds Channel 3 range.   Factory set to 0x0001.     40100   Setup Channel 4   R/W   0-F   Holds Channel 4 range.   Factory set to 0x0001.     40101   Setup Channel 5   R/W   0-F   Holds Channel 5 range.   Factory set to 0x0001.     40102   Setup Channel 6   R/W   0-F   Holds Channel 6 range.   Factory set to 0x0001.     40103   Setup Channel 7   R/W   0-F   Holds Channel 7 range.   Factory set to 0x0001.     40114   Trim Zero, 10V   WP   0   Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	40098	Setup Channel 2	K/VV	U-F		
Factory set to 0x0001.  40100 Setup Channel 4 R/W 0-F Holds Channel 4 range. Factory set to 0x0001.  40101 Setup Channel 5 R/W 0-F Holds Channel 5 range. Factory set to 0x0001.  40102 Setup Channel 6 R/W 0-F Holds Channel 6 range. Factory set to 0x0001.  40103 Setup Channel 7 R/W 0-F Holds Channel 7 range. Factory set to 0x0001.  40114 Trim Zero, 10V WP 0 Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	40000	0.101	D ***	0.5		
40100 Setup Channel 4 R/W 0-F Holds Channel 4 range. Factory set to 0x0001.  40101 Setup Channel 5 R/W 0-F Holds Channel 5 range. Factory set to 0x0001.  40102 Setup Channel 6 R/W 0-F Holds Channel 6 range. Factory set to 0x0001.  40103 Setup Channel 7 R/W 0-F Holds Channel 7 range. Factory set to 0x0001.  40114 Trim Zero, 10V WP 0 Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	40099	Setup Channel 3	K/W	U-F		
Factory set to 0x0001.  40101 Setup Channel 5 R/W 0-F Holds Channel 5 range. Factory set to 0x0001.  40102 Setup Channel 6 R/W 0-F Holds Channel 6 range. Factory set to 0x0001.  40103 Setup Channel 7 R/W 0-F Holds Channel 7 range. Factory set to 0x0001.  40114 Trim Zero, 10V WP 0 Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	40400	Catum Ola and 1 4	D/4/			
40101 Setup Channel 5 R/W 0-F Holds Channel 5 range.  Factory set to 0x0001.  40102 Setup Channel 6 R/W 0-F Holds Channel 6 range.  Factory set to 0x0001.  40103 Setup Channel 7 R/W 0-F Holds Channel 7 range.  Factory set to 0x0001.  40114 Trim Zero, 10V WP 0 Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	40100	Setup Channel 4	K/VV	U-F		
Factory set to 0x0001.  40102 Setup Channel 6 R/W 0-F Holds Channel 6 range. Factory set to 0x0001.  40103 Setup Channel 7 R/W 0-F Holds Channel 7 range. Factory set to 0x0001.  40114 Trim Zero, 10V WP 0 Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	40404	0-6	D // /			
40102     Setup Channel 6     R/W     0-F     Holds Channel 6 range.       40103     Setup Channel 7     R/W     0-F     Holds Channel 7 range.       40114     Trim Zero, 10V     WP     0     Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	40101	Setup Channel 5	K/W	U-F		
Factory set to 0x0001.  40103 Setup Channel 7 R/W 0-F Holds Channel 7 range. Factory set to 0x0001.  40114 Trim Zero, 10V WP 0 Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	40400	Cotum Objective LO	D/4/	^ -		
40103 Setup Channel 7 R/W 0-F Holds Channel 7 range. Factory set to 0x0001.  40114 Trim Zero, 10V WP 0 Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	40102	Setup Channel 6	K/W	U-F		
Factory set to 0x0001.  40114 Trim Zero, 10V WP 0 Forces all Channel Data Registers to 8000h, with input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	40400	0.401	D 4.4.			
40114 Trim Zero, 10V WP 0 Forces all Channel Data Registers to 8000h, with Input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	40103	Setup Channel 7	K/W	U-F		
Range input signal equal to zero. Apply calibration signal at least 15 seconds prior to calibrating to all	10111	T : 7 (0)	14/5			
at least 15 seconds prior to calibrating to all	40114		WP	0		
	1	Range				
Convigint Dutile Glines and Higgins Corporation 2021 All Rights Reserved						

			1	
				channels. Calibration Acknowledge Exception
	,			Response. Calibration takes 20 seconds.
40115	Trim Zero, 5V Range	WP	0	Refer to Modbus register 40072.
40116	Trim Zero, 1V Range	WP	0	Refer to Modbus register 40072.
40117	Trim Zero, 0.1V Range	WP	0	Refer to Modbus register 40072. Apply calibration signal at least 1 minute prior to calibrating to all channels.
40118	Trim Zero, 0.05V Range	WP	0	Refer to Modbus register 40072. Apply calibration signal at least 1 minute prior to calibrating to all channels.
40119	Trim Zero, 0.025V Range	WP	0	Refer to Modbus register 40072. Apply calibration signal at least 1 minute prior to calibrating to all channels.
40129	Trim CJC 0	WP	0-1	Pre-calibrate appropriate mV range. Attach thermocouple to channel 1, with measurement end in ice bath. Writing a 1 will increase Modbus TC output. Writing a 0 will decrease Modbus TC output.  No Trim for R, S, B, C Types.
40130	Trim CJC 1	WP	0-1	Pre-calibrate appropriate mV range. Attach thermocouple to channel 5, with measurement end in ice bath. Writing a 1 will increase Modbus TC output. Writing a 0 will decrease Modbus TC output.  No Trim for R, S, B, C Types.
40146	Trim FS, 10V Range	WP	D000- FFFE	Forces all Channel Data Registers to written value, with appropriate input signal. Apply calibration signal at least 15 seconds prior to calibrating to all channels. Acknowledge Exception Response. Calibration takes 20 seconds. See note 1.
40147	Trim FS, 5V Range	WP	D000- FFFE	See Modbus Register 40146.
40148	Trim FS, 1V Range	WP	D000- FFFE	See Modbus Register 40146.
40149	Trim FS, 0.1V Range	WP	D000- FFFE	See Modbus Register 40146. Apply calibration signal at least 1 minute prior to calibrating to all channels.
40150	Trim FS, 0.05V Range	WP	D000- FFFE	See Modbus Register 40146. Apply calibration signal at least 1 minute prior to calibrating to all channels.
40151	Trim FS, 0.025V Range	WP	D000- FFFE	See Modbus Register 40146. Apply calibration signal at least 1 minute prior to calibrating to all channels.
40241	Control Register	W		<ul> <li>0 – Normal operation (NOP)</li> <li>1 – Remote Reset (write protected)</li> <li>2 – Write Enable</li> <li>5 – Initialize Host Communication setup</li> </ul>

Functions:

R Read Only
R/W Read/Write WP Write-Protected

### 5.4.4 Seven Channel Voltage, Thermocouple and Current Input Calibration Procedure

### **Required Equipment:**

- 1. Computer running the DGH Utility Software or another Modbus Master program.
- 2. A NIST traceable DC Voltage Standard with +/-10Vdc range.

### **Setup Steps – Perform Calibration Steps in Order Listed:**

- 1. Allow unit to warm up for 15 minutes.
- 2. Short all the +Input pins together using short jumper wires.
- 3. Short all the -Input pins together using short jumper wires.
- 4. Connect the +Input wires to the Positive terminal on the DC voltage calibrator.
- 5. Connect the -Input wires to the Negative terminal on the DC voltage calibrator.
- 6. Install the DGH Utility Software or another Modbus Master Program to communicate with, and calibrate with the module via serial port or a TCP/IP connection.

#### Trim Zero:

- 1. Set the DC calibrator voltage output to +0.0000Vdc.
- 2. Use the DGH Utility Software or a Modbus Master program to perform steps #3 & #5.
- 3. Set all channels to the same range. Start with +/-10Vdc range, work downward as per values in Table 1.0.
- 4. Trim Zero on all channels.
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Retrieve Trim Zero register value for specific range from Table 2.0 below.
  - c. Write value of 0x00h to Range Trim Zero register, (ie. 40114 for +/-10V).
  - d. Perform steps #4a through #4c to trim zero on each range.

### Trim Span:

- 1. Set the DC calibrator voltage output to +10.000Vdc.
- 2. Use the DGH Utility Software or a Modbus Master program to perform steps #3 & #5.
- 3. Set all channels to the same range. Start with +/-0.025Vdc range, work upward as per values in Table 3.0.
- 4. Trim Span on each channel.
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Retrieve Trim Span register value for specific range from Table 2.0 below.
  - c. Write value of 0xfffe to Trim Span register, (ie. 40146 for +/-10V).
  - d. Perform steps #4a through #4c to trim span on each range.

### Trim CJC's:

- 1. Set the input signal to ----.
- 2. Set all module channels to the J-Thermocouple range.
- 3. Use the DGH Utility Software or a Modbus Master program to perform steps #4 & #5.
- 4. Trim Zero on each input channel
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Write a value of 0x0000h to register 40114.
- 5. Apply input signal to each channel from Table x.xx.
  - a. Wait 1 minute.
  - b. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - c. Write a value of 0xfffe

## Trim Thermocouples:

- 1. Set the input signal to ----.
- Set all module channels to the J-Thermocouple range.
   Use the DGH Utility Software or a Modbus Master program to perform steps #4 & #5.
- 4. Trim Zero on each input channel
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Write a value of 0x0000h to register 40114.
- 5. Apply input signal to each channel from Table x.xx.

  - a. Wait 1 minute.
    b. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - **c.** Write a value of 0xfffe

### 5.4.5 Seven Channel Voltage, Thermocouple and Current Input Calibration Tables:

Seven Channel Range Register Values							
Channel	Range Control	R	tange Values				
Channel 1	40097	00	Disabled				
Channel 2	40098	01	+/-10V				
Channel 3	40099	02	+/-5V				
Channel 4	40100	03	+/-1V				
Channel 5	40101	04	+/-0.1V				
Channel 6	40102	05	+/-0.05V				
Channel 7	40103	06 +/-0.025V					
•		21	J-Type TC				
		22	K-Type TC				
		23	T-Type TC				
		24	E-Type TC				
		25	R-Type TC				
		26	S-Type TC				
		27	B-Type TC				
		28	C-Type TC				

Table 1.0 Register Setup Values.

Trim Zero Registers and Calibration Values								
Range Register Value								
+/-10Vdc	40114	0000						
+/-5Vdc	40115	0000						
+/-1Vdc	40116	0000						
+/-0.1Vdc	40117	0000						
+/-0.05Vdc	40118	0000						
+/-0.025Vdc	40119	0000						

Table 2.0 Trim Zero Registers and Values.

Trim Span Registers and Calibration Values				
Range	Register	<u>Value</u>		
+/-0.025Vdc	40151	FFFE		
+/-0.05Vdc	40150	FFFE		
+/-0.1Vdc	40149	FFFE		
+/-1Vdc	40148	FFFE		
+/-5Vdc	40147	FFFE		
+/-10Vdc	40146	FFFE		

Table 3.0 Trim Span Registers and Values.

CJC Calibration Registers and Values				
Channels Register Increase Value Decrease Value				
03	40129	0001	0000	
46	40130	0001	0000	

Table 4.0 Trim CJC Registers and Values.

### 5.4.6 D7400 Current Channel Enable:

#### Overview

The following information details how to open the D7400 module and enable or disable current channels.

### **Default from the Factory**

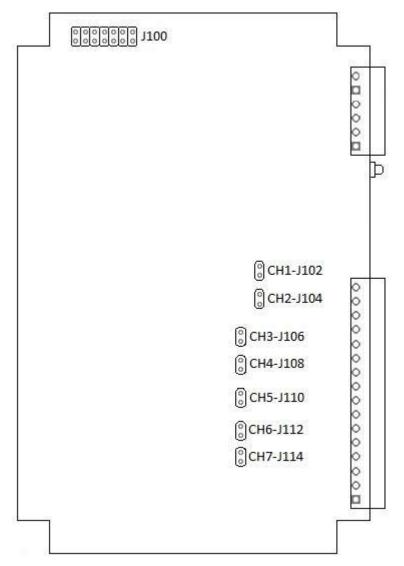
No current enabling jumpers are installed at the factory. All channels are initialized as voltage inputs.

### **Open the Module**

Remove the top cover of the D7400 module by unscrewing the four screws on the top cover. With the cover removed, locate J100, a storage strip that contains up to seven unused jumpers. Then locate the CH1 through CH7 jumper strips that enable current channels.

### Move the Jumpers

To enable any channel as a current input channel, simply move a jumper from J100 to the specific channel jumper strip. To disable a current input channel, simply move the jumper from the channel jumper strip back to J100. See the image below for the location of the pin strips versus channels.



### 5.5 D7500 Two Channel Analog Output Module

#### Overview

The D7500 series analog output module contains two 12-bit analog outputs for controlling process control devices. Each analog output signal can be configured as either a voltage or current output. Two voltage ranges and two current ranges can be selected for maximum flexibility to control many different process control devices.

### **Analog Outputs**

The D7500 series analog outputs can be configured as either voltage outputs or current outputs.

### **Features and Register Assignments**

The D7500 series modules contain many user-selectable features. The user can select all features such as baud rate, parity type, power-on "safe" analog output value and communications watchdog timer interval. The complete list of features is illustrated in the "Two Channel Analog Output Register Assignments" register map below. The register map format is used for consistency with the Modbus RTU protocol. The register map contains the register numbers in decimal format, register description, acceptable data values, and list of what each value means. These registers can be written to using most any Modbus master program or using the DGH D6000 series utility software.

Note: All Modbus Register values in the tables below are represented as "decimal" numbers.

### **Factory Initial Values**

The D7700 series analog output modules are initialized at the factory with a set of "Initial Values". A complete list of factory "Initial Values" can be found in the table below.

### **Communications Watchdog Timer**

The D7500 series digital output module contains a user-programmable communications watchdog timer. The communications watchdog timer can be used to force the analog output signals to a known "safe" condition in the event that communications are lost to the module. The known "safe" condition can be user-programmed into the module Initial Value register.

#### **Connector Pin Designations**

The D7500 series module uses two 3.81mm removable plugs for connecting signals to the module. One two-pin connector is for the power supply connections. A second eight-pin connector is used to connect analog output signals to control devices. The <u>pin designations</u> for each connector are printed on the module label and are listed in a table below.

### 5.5.1 Two Channel Analog Output Pin Assignments and Specifications

### Connections

### **Power & Serial Communications**

Pin Number	<u>Pin</u>	<u>Designator</u>
1	GND	- Power Supply
2	+VS	+ Power Supply

### **Analog Output Pin Assignments**

Pin Number	<u>Pin</u>	<u>Designator</u>
1	CH1 +I	#1-+Current Out
2	CH1 -I	#1Current Out
3	CH1 +V	#1- +Voltage Out
4	CH1 -V	#1Voltage Out
5	CH2 +I	#2- +Current Out
6	CH2 -I	#2Current Out
7	CH2 +V	#2- +Voltage Out
8	CH2 -V	#2Voltage Out

### Notes:

- 1. Each channel can be used as either a voltage output or a current output. But not both at the same time.
- 2. When using a channel as a current output there must be no connections on +/-V Output pins.

### **Specifications**

Analog Outputs	2 Channels
User Selectable Inpu Voltage Ranges Current Ranges	t Ranges 0-10V, +/-10V, 4-20mA, 0-20mA

Protocol TCP	Modbus TCP/IP
Power Supply Voltage Power	+10-30Vdc 2.1W
Connectors Spacing Max Wire Size Max Current	3.81mm 14-24 AWG 8 Amperes

Serial LED Displays
Transmit (Top)
TxData
Receive (Bottom)
RxData

## **5.5.2 Two Channel Analog Output Register Assignments**

Register	Description	Functions	<u>Value</u>	<u>Description</u>
40001	Slave Address	R/WP	1-DF	Factory set to 0x0001.
40002	UART Setup	R/WP	5-9	Factory set to 0x0035 = 9600, 8, N, 1.
40003	Modbus Delays	R/WP	0-303F	Bits 0-7 The Response Delay in milliseconds. This is required when the RS-485 adapter cannot tristate immediately after the last character is transmitted from the host. Maximum value is 63mS. Factory default value is 3.
				Bits 8-15 The End of Query Delay in milliseconds (48mS max). This is an additional time that the module will wait prior to marking the end of the message. Slower host computers may not be able transmit a continuous message stream, thereby creating gaps between characters exceeding the normal 3.5 character times limit. Factory default value is 0.  Factory set to 0x0003.
40033	Software Version	R		Factory set from data value in source code.
40049	Analog Out CH1	R/W	0-FFFF	0= -FS, FFFF= +FS, Set analog output, DAC
40050	Analog Out Ch2	R/M	0-EEEE	value after slewing.
40050 40065	Analog Out Ch2 Slope CH1	R/W R/W	0-FFFF 0-12	See Register 49.  On the fly slope. Reset default slope from EEPROM.  0 - Immediate 1 - 0.156% Span/s 2 - 0.310 3 - 0.625 4 - 1.25 5 - 2.50 6 - 5 7 - 10 8 - 20 9 - 40 A - 80 B - 160 C - 320 D - 640 E - 1280 F - 2560 10 - 5120 11 - 10240 12 - 20480 V/S=% Span/s (Span)/100 i.e. for slope= 10, 5120(10)/100=512V/S
40066	Slope CH2	R/W	0- 1FFFF	On the fly slope.  Factory set to 0x0000.
40097	ADC Read CH1	R	0-FFFF	Readback CH1, 8 bit resolution.
40098	ADC Read CH2	R		Readback CH2, 8 bit resolution.
40113	Present Output CH1	R	0-FFFF	Normalized present DAC value. Present Output may differ from Setpoint, if output has not reached to its final value.
40114	Present Output CH2	R	0-FFFF	Normalized present DAC value. Present Output may differ from Setpoint, if output has not reached to its final value.

10111		5.445		
40144	Watchdog Time-	R/WP	0-FFFF	The interval of time in seconds that must lapse
	out Interval			after the last communication to the module or
				since power was applied, before the Watchdog
				is triggered and the outputs are set to the Initial
				Value. Effective immediately. The purpose of
				the Watchdog Timer is to force the analog
				outputs to a known safe value in the event of a
				host or communications link failure. The
				Watchdog Timer may be disabled, by setting
				the value to FFFF Hex. Accuracy is 10%.
				Factory set to 0xFFFF.
40145	Setup CH1	R/WP		Holds Channel 1 range and slope setup. On the
40140	Octup Offi	1 (7 ) (7 )		fly slope changed immediately. Setup change is
				immediate.
				Bits 0-2
				0 – 0-10V
				1 – +/-10V
				2 – 4-20mA
				3 – 0-20mA
				Bits 3-7
				0 – Immediate
				1 – 0.156% Span/s
				2 – 0.31
				3 – 0.625
				4 – 1.25
				5 – 2.50
				6-5
				7 – 10
				8 – 20
				9 – 40
				A – 80
				B –160
				C – 320
				D - 640
				E – 1280
				F – 2560
				10 – 5120
				11 – 10240
				12 – 20480
				V/S=% Span/s (Span)/100
				i.e. for slope= 10, 5120(10)/100=512V/S
				Factory set to 0x0000.
40146	Initial Value CH1	R/WP	0-FFFF	Power-Up or Reset analog output value.
10140	Antical Value Of 11			Factory set to 0x0000.
40147	Setup CH2	R/WP	<del>                                     </del>	Holds Channel 2 range and slope setup.
40147	Setup CHZ	IN/VVP		
40440	Initial Value OUG		0 5555	Factory set to 0x0000.
40148	Initial Value CH2	R/WP	0-FFFF	Power-Up or Reset analog output value.
45.5==				Factory set to 0x0000.
40177	Increase Min	WP	0-1	Increases output of selected channel, by 1
	Output			LSB. Output must be previously set to
	Calibration			minimum value in table xx. Repeat as needed
				get the desired output. The effect is immediate.
				Write 0 for Channel 1
				Write 1 for Channel 2
40178			0-1	Decreases output of selected channel, by 1
	Decrease Min	WP	I U-I	
	Decrease Min Output	WP	0-1	
	Output	WP	0-1	LSB. Output must be previously set to minimum
		WP	0-1	LSB. Output must be previously set to minimum value in table xx. Repeat as needed to get
	Output	WP	0-1	LSB. Output must be previously set to minimum value in table xx. Repeat as needed to get desired output. The effect is immediate.
	Output	WP	0-1	LSB. Output must be previously set to minimum value in table xx. Repeat as needed to get

40179	Increase Max Output Calibration	WP	0-1	Increases output of selected channel, by 1 LSB. Output must be previously set to maximum value in table xx. Repeat as needed get the desired output. The effect is immediate.  Write 0 for Channel 1 Write 1 for Channel 2
40180	Decrease Max Output Calibration	WP	0-1	Decreases output of selected channel, by 1 LSB. Output must be previously set to maximum value in table xx. Repeat as needed to get desired output. The effect is immediate.  Write 0 for Channel 1  Write 1 for Channel 2
40181	Trim ADC	WP	0-1	Forces output of selected channel (data value) to minimum and maximum values momentarily, and calibrates readback ADC to coincide.  Output is then restored to original value when calibration is completed. The effect is immediate.
40241	Control	W		<ul> <li>0 – Normal operation (NOP)</li> <li>1 – Remote Reset (write protected)</li> <li>2 – Write Enable</li> <li>5 – Initialize Host communications setup</li> </ul>

Functions:

R Read Only
R/W Read/Write WP Write-Protected

### Notes:

Values written to Registers 40049 and 40050 must not be proceeded by a Write-Protect 1. command.

## **5.5.3 Two Channel Analog Output Initial Factory Values**

Module Parameter	<u>Value</u>
Slave Address*	1
Baud Rate*	9600
Parity Type*	None
Modbus Response Delay	3mS
Modbus Query Delay	0mS
Conversion Rate	60Hz
Channel 0 on the fly slope	Immediate
Channel 1 on the fly slope	Immediate
Watchdog Timer Low Word	0xffff, = Disabled
Channel 0 Range	0-10Vdc
Channel 0 Slope	Immediate
Channel 0 Initial Value	0Vdc
Channel 1 Range	0-10Vdc
Channel 1 Slope	Immediate
Channel 1 Initial Value	0Vdc

<sup>\* =</sup> These values should not be changed.

### 5.5.4 Analog Voltage Output Calibration Procedure

### **Required Equipment**

- 1. Computer running the DGH Utility Software or another Modbus Master program.
- 2. A NIST traceable Digital multimeter (DMM) with +/-10Vdc range.

### **Setup Steps – Perform Calibration Steps in Order Listed:**

- 1. Allow unit to warm up for 15 minutes.
- 2. Connect positive (+) lead of the DMM to the Ch1+Vout terminal.
- 3. Connect negative (-) lead of the DMM to the Ch1 IsoGnd terminal.
- 4. Install the DGH Utility Software or another Modbus Master Program to communicate with, and calibrate with the module via serial port or a TCP/IP connection.
- 5. Remove all connections to the +lout and –lout terminals on Ch1 and Ch2.

### Trim Negative Full Scale:

- 1. Using the DGH Utility Software configure both Ch1 and Ch2 analog output ranges to the +/-10Vdc range. See Table 1.0 below for register and data values.
- 2. Use the DGH Utility Software set Ch1 and Ch2 analog outputs to their –Full Scale value. See Table 2.0 below for register and data values.
- 3. Trim Negative Full Scale.
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Trim the Negative Full Scale output using the register and data value in Table 3.0 below. Write value the channel value to the proper register to increase or decrease the analog output signal to match the –Full Scale output value.
- 4. Move the DMM leads to the Ch2 +Vout and IsoGnd terminals.
- 5. Repeat steps 3a and 3b to trim the negative full-scale output of Ch2.

#### **Trim Positive Full Scale:**

- 1. Move the DMM leads to the Ch1 +Vout and –Vout terminals.
- 2. Use the DGH Utility Software set Ch1 and Ch2 analog outputs to their +Full Scale value. See Table 2.0 below for register and data values.
- 3. Trim Positive Full Scale.
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Trim the Positive Full Scale output using the register and data value in Table 4.0 below. Write value the channel value to the proper register to increase or decrease the analog output signal to match the +Full Scale output value.
- 4. Move the DMM leads to the Ch2 +Vout and IsoGnd terminals.
- 5. Repeat steps 3a and 3b to trim the positive full-scale output of Ch2.

Using the DGH Utility Software set the Ch1 and Ch2 analog output ranges to +10Vdc range. Repeat steps above calibrate the 0-10Vdc range.

### 5.5.5 Analog Current Output Calibration Procedure

### Required Equipment

- 1. Computer running the DGH Utility Software or another Modbus Master program.
- 2. A NIST traceable Digital multimeter (DMM) with 0-20mA range.

### **Setup Steps – Perform Calibration Steps in Order Listed:**

- 1. Allow unit to warm up for 15 minutes.
- 2. Connect positive (+) lead of the DMM to the Ch1 +lout terminal.
- 3. Connect negative (-) lead of the DMM to the Ch1 -lout terminal.
- 4. Install the DGH Utility Software or another Modbus Master Program to communicate with, and calibrate with the module via serial port or a TCP/IP connection.
- 5. Remove all connections to the +Vout and –Vout terminals on Ch1 and Ch2.

### Trim Negative Full Scale:

- 1. Using the DGH Utility Software configure both Ch1 and Ch2 analog output ranges to the 0-20mA range. See Table 1.0 below for register and data values.
- 2. Use the DGH Utility Software set Ch1 and Ch2 analog outputs to their –Full Scale value. See Table 2.0 below for register and data values.
- 3. Trim Negative Full Scale.
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Trim the Negative Full Scale output using the register and data value in Table 3.0 below. Write value the channel value to the proper register to increase or decrease the analog output signal to match the –Full Scale output value.
- 4. Move the DMM leads to the Ch2 +lout and –lout terminals.
- 5. Repeat steps 3a and 3b to trim the negative full-scale output of Ch2.

#### **Trim Positive Full Scale:**

- 1. Move the DMM leads to the Ch1 +lout and -lout terminals.
- 2. Use the DGH Utility Software set Ch1 and Ch2 analog outputs to their +Full Scale value. See Table 2.0 below for register and data values.
- 3. Trim Positive Full Scale.
  - a. Write a value of 0x0002h to Control Register 40241 to Write-Enable the module.
  - b. Trim the Positive Full Scale output using the register and data value in Table 4.0 below. Write value the channel value to the proper register to increase or decrease the analog output signal to match the +Full Scale output value.
- 4. Move the DMM leads to the Ch2 +lout and -lout terminals.
- 5. Repeat steps 3a and 3b to trim the positive full-scale output of Ch2.

Using the DGH Utility Software set the Ch1 and Ch2 analog output ranges to 4-20mA range. Repeat steps above to calibrate the 4-20mA range.

### 5.5.6 Analog Output Calibration Register Tables and Values

Channel Range Registers and Values				
Channel	Range Control	Range Values		
Channel 1	40145	0 = 0-10Vdc		
Channel 2	40146	1 = +/-10Vdc		
		2 = 4-20mA		
		3 = 0-20mA		

Table 1.0 Analog Output Range Registers and Values.

Analog Output Registers					
<u>Channel</u> <u>Register</u> <u>Force -FS Output</u> <u>Force +FS Output</u>					
Channel 1	40049	0000	FFFF		
Channel 2	40050	0000	FFFF		

Table 2.0 Analog Output Register and Calibration Values.

Trim Negative Full Scale Calibration Registers and Values				
<u>Register</u>	-Full Scale Output Adjust	<u>CH1</u>	<u>CH2</u>	
40177	Increase Signal	0000	0001	
40178	Decrease Signal	0000	0001	

 Table 3.0 Trim Negative Full Scale Calibration Registers and Values.

Trim Positive Full Scale Calibration Registers and Values				
<u>Register</u>	+Full Scale Signal Adjust	<u>CH1</u>	<u>CH2</u>	
40179	Increase Signal	0000	0001	
40180	Decrease Signal	0000	0001	

 Table 4.0 Trim Positive Full Scale Calibration Registers and Values.

### 5.6 D7710 - Fifteen Bit Digital Input Module

#### Overview

The D7710 series module contains fifteen digital inputs to monitor process signals such as logic-level status, relay contacts, switch closures, and dry-contacts.

### **Digital Inputs**

The D7710 digital input bits accept signals between +/-30Vdc without damage and contain internal 10K pull-up resistors for direct connection to dry-contacts.

The digital input logic level switching levels are less than 1.0Vdc for logic "0" and greater than +3.5Vdc for a logic "1".

### **Features and Register Assignments**

The D7710 series digital input modules contain many user-selectable features. The complete list of features is illustrated in the "<u>Fifteen Bit Digital I/O Register Assignments</u>" map below. The register map format is used for consistency with the Modbus RTU protocol. The register map contains the register numbers in decimal format, register description, acceptable data values, and list of what each value means. These registers can be written to using most any Modbus master program or using the DGH D6000 series utility software.

Note: All Modbus Register values in the tables below are represented as "decimal" numbers.

### **Connector Pin Designations**

The D7710 series module uses two 3.81mm removable plugs for connecting signals to the module. One two-pin connector is for the power supply connections. A second sixteen-pin connector is used to connect digital signals to the module. The <u>pin designations</u> for each connector are printed on the module label and are listed in a table below.

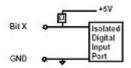
### 5.6.2 Fifteen Bit Digital Input Specifications

### Connections

### **Power and Serial Communications**

<u>Pin Number</u>	<u>Pin</u>	<u>Designator</u>
1	GND	- Power Supply
2	+VS	+ Power Supply

## **Typical Input**



### **Digital Input Pin Assignments**

Bit Number	Pin Designator
1	B01
2	B02
3	B03
4	B04
5	B05
6	B06
7	B07
8	B08
9	B09
10	B10
11	B11
12	B12
13	B13
14	B14
15	B15
16	ISO. GND

### **Specifications**

Specifications	
Digital Inputs	15
Input Bit Internal Pull-up Max Voltage Logic '0' Logic '1'	10K to +5Vdc +/-30Vdc <1.0Vdc >3.5Vdc
Isolation GND to IGND	500Vrms
Protocol TCP	Modbus TCP/IP
Power Supply Voltage Power	+10-30Vdc 0.75W
Connectors Spacing Max Wire Size Max Current	3.81mm 14-24 AWG 8 Amperes
LED Designators 01-15 F T R	Bit LO = On Always Off TxData RxData
LED Display	
<u>(13)</u> 9	5 1

• •			Totald			
LED Dis	play					
<u>(13)</u>	9	5	1			
(14)	10	6	2			
<b>(15)</b>	11)	1	3	T		
$\bigcirc$	(12)	(8)	<b>(4)</b>	$\widehat{R}$		

Digital Input/Output LEDS

### 5.6.3 Fifteen Bit Digital Input Initial Factory Values

Module Parameter	<u>Value</u>
Slave Address*	1
Baud Rate*	9600
Parity Type*	None
Modbus Response Delay	3mS
Modbus Query Delay	0mS

<sup>\* =</sup> These values should not be changed.

### 5.6.4 Fifteen Bit Digital Input Register Assignments

Register	Description	<u>Functions</u>	<u>Value</u>	<u>Description</u>
40001	Slave Address	R/WP	1-DF	Factory set to 0x0001.
40002	UART Setup	R/WP		Factory set to 0x0035 = 9600, 8, N, 1.
40003	Modbus Delays	R/WP	0-303F	Bits 0-7 The Response Delay in milliseconds. This is required when the RS-485 adapter cannot tristate immediately after the last character is transmitted from the host. Maximum value is 63mS. Factory default value is 3.  Bits 8-15 The End of Query Delay in milliseconds (48mS max). This is an additional time that the module will wait prior to marking the end of the message. Slower host computers may not be able transmit a continuous message stream, thereby creating gaps between characters exceeding the normal 3.5 character times limit. Factory default value is 0.  See Note 2. Factory set to 0x0003.
40033	Software Version	R		Factory set, Code Version.
40241	Control Register	W		0 – Normal operation (NOP)
				1 – Remote Reset (write protected)
				2 – Write Enable
				3 – Synchronous Data sample
				5 – Init Host Com Setup

Functions:

R Read Only
R/W Read/Write WP Write-Protected

Discrete Coil (DI) Mapping Table			
Address (hex)	Channel #	Coil #	Using Function Codes 01 and 02
0	0	1	"
1	1	2	ű
2	2	3	ű
:			
15	15	15	и
100	0	1	Sync Input Data
101	1	2	"
102	2	3	"
:			u .
10E	14	15	"

#### 5.7 D7720 - Fifteen Bit Digital Output Module

#### Overview

The D7720 series digital output module contains fifteen digital outputs for controlling process control devices such as relays, lamps, annunciators and other ON/OFF devices.

#### **Digital Outputs**

The D7720 series open-collector digital outputs can be pulled up to +30Vdc max and each bit can sink up to 100mA. The open-collector output provides maximum flexibility to control many different process control devices.

#### **Features and Register Assignments**

The D7720 series digital output modules contain many user-selectable features. The complete list of features is illustrated in the "<u>Fifteen Bit Digital I/O Register Assignments</u>" register map below. The register map format is used for consistency with the Modbus RTU protocol. The register map contains the register numbers in decimal format, register description, acceptable data values, and list of what each value means. These registers can be written to using most any Modbus master program or using the DGH D6000 series utility software.

Note: All Modbus Register values in the tables below are represented as "decimal" numbers.

#### **Factory Initial Values**

The D7720 series digital output modules are initialized at the factory with a set of "Initial Values". A complete list of factory "Initial Values" can be found in the table below.

#### **Communications Watchdog Timer**

The D7720 series digital output module contains a user-programmable communications watchdog timer. The communications watchdog timer can be used to force the digital outputs to a known "safe" condition in the event of a communications lost to the module. The known "safe" condition can be user-programmed into the module Initial Value register.

#### **Connector Pin Designations**

The D7720 series module uses two 3.81mm removable plugs for connecting signals to the module. One two-pin connector is for the power supply connections. A second sixteen-pin connector is used to connect digital signals to the module. The <u>pin designations</u> for each connector are printed on the module label and are listed in a table below.

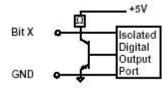
### 5.7.2 Fifteen Bit Digital Output Specifications

### Connections

### **Power and Serial Communications**

Pin Number	<u>Pin</u>	<u>Designator</u>
1	GND	- Power Supply
2	+VS	+ Power Supply

## **Typical Output Circuit**



### **Digital Output Pin Assignments**

Bit Number	Pin Designator
1	B01
2	B02
3	B03
4	B04
5	B05
6	B06
7	B07
8	B08
9	B09
10	B10
11	B11
12	B12
13	B13
14	B14
15	B15
16	ISO. GND

### **Specifications**

Digital Outputs	15
Output Bit Open-Collector Vsat Short Circuit Type	30Vdc, 100mA 0.3V @ 100mA 500mA max Sinking
Isolation GND to IGND	500Vrms
Watchdog Timer Range Resolution	0 to 655.35 Sec 0.35 Sec
Protocol TCP	Modbus TCP/IP

_	
Power Supply Voltage Power	+10-30Vdc 1.0W
Connectors Spacing Max Wire Size Max Current	3.81mm 14-24 AWG 8 Amperes
LED Designators 01-15 F T	Bit LO = On Always Off TxData

### LED Display

R

(13)	•	(5)	$\odot$	
14)	10	6	2	
<u>(15)</u>	11)	1	3	(7)
$\bigcirc$	12	8	4	$\bigcirc$ R

RxData

Digital Input/Output LEDS

### 5.7.3 Fifteen Bit Digital Output Initial Factory Values

Module Parameter	<u>Value</u>
Slave Address*	1
Baud Rate*	9600
Parity Type*	None
Modbus Response Delay	3mS
Modbus Query Delay	0mS
Digital Output Initial Value	0x0000 = All Outputs Off
Watchdog Timer Low Word	0xffff, = Disabled

<sup>\* =</sup> These values should not be changed.

### 5.7.4 Fifteen Bit Digital Output Register Assignments

Register	Description	<u>Functions</u>	<u>Value</u>	<u>Description</u>
40001	Slave Address	R/WP	1-DF	Factory set to 0x0001.
40002	UART Setup	R/WP		Factory set to 0x0035 = 9600, 8, N, 1.
40003	Modbus Delays	R/WP	0-303F	Bits 0-7 The Response Delay in milliseconds. This is required when the RS-485 adapter cannot tristate immediately after the last character is transmitted from the host. Maximum value is 63mS. Factory default value is 3.  Bits 8-15 The End of Query Delay in milliseconds (48mS max). This is an additional time that the module will wait prior to marking the end of the message. Slower host computers may not be able transmit a continuous message stream, thereby creating gaps between characters exceeding the normal 3.5 character times limit. Factory default value is 0.  See Note 2.
40033	Software Version	R		Factory set to 0x0003.  Factory set, Code Version.
40096	Watchdog Timer Interval	R/WP	0.FFFF	The interval of time in seconds that must elapse after the last communication to the module or since the power was applied, before the outputs are set to the Initial Value. The purpose of the Watchdog Timer is to force the digital outputs to a known safe value in the event of a host or communications link failure. The Watchdog Timer may be disabled by setting the value to 0xFFFF hex.  Factory set to 0xFFFF.
40097	Initial Value	R/WP	0.FFFF	Starting condition of Coils 1-15. Bit #0 is Ch0. Initial Value bits set to Logic 1 will be initialized to the "On" state. Bits set to Logic 0 will be initialized to the "Off" state.  Factory Set to 0x0000.
40241	Control Register	W		<ul> <li>0 – Normal operation (NOP)</li> <li>1 – Remote Reset (write protected)</li> <li>2 – Write Enable</li> <li>3 – Synchronous Data sample</li> <li>5 – Init Host Com Setup</li> </ul>

Discrete Coil (DI) Mapping Table			
Address (hex)	Channel #	Coil#	Using Function Codes 01 and 02
0	0	1	u
1	1	2	u
2	2	3	u
:			
E	E	E	и
100	0	1	Sync Input Data
101	1	2	u
102	2	3	и
:			11
10E	14	15	"

### **Functions:**

R Read Only
R/W Read/Write
WP Write-Protected

#### 5.8 D7730 - Seven Digital Input and Eight Digital Output Module

#### Overview

The D7730 series digital input/output module contains seven digital inputs and eight digital outputs for controlling process control devices such as relays, lamps, annunciators and other ON/OFF devices.

#### **Digital Inputs**

The D7730 digital input bits accept signals between +/-30Vdc without damage and contain internal 10K pull-up resistors for direct connection to dry-contacts.

The digital input logic level switching levels are less than 1.0Vdc for logic "0" and greater than +3.5Vdc for a logic "1".

#### **Digital Outputs**

The D7730 series open-collector digital outputs can be pulled up to +30Vdc max and each bit can sink up to 100mA. The open-collector output provides maximum flexibility to control many different process control devices.

#### **Features and Register Assignments**

The D7730 series digital input/output modules contain many user-selectable features. The complete list of features is illustrated in the "<u>Fifteen Bit Digital I/O Register Assignments</u>" register map below. The register map format is used for consistency with the Modbus RTU protocol. The register map contains the register numbers in decimal format, register description, acceptable data values, and list of what each value means. These registers can be written to using most any Modbus master program or using the DGH D6000 series utility software.

Note: All Modbus Register values in the tables below are represented as "decimal" numbers.

#### **Factory Initial Values**

The D7730 series digital output modules are initialized at the factory with a set of "Initial Values". A complete list of factory "Initial Values" can be found in the table below.

#### **Communications Watchdog Timer**

The D7730 series digital output module contains a user-programmable communications watchdog timer. The communications watchdog timer can be used to force the digital outputs to a known "safe" condition in the event of a communications lost to the module. The known "safe" condition can be user-programmed into the module Initial Value register.

#### **Connector Pin Designations**

The D7730 series module uses two 3.81mm removable plugs for connecting signals to the module. One two-pin connector is for the power supply connections. A second sixteen-pin connector is used to connect digital signals to the module. The <u>pin designations</u> for each connector are printed on the module label and are listed in a table below.

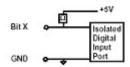
### 5.8.2 Fifteen Bit Digital Output Specifications

### Connections

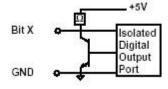
### **Power and Serial Communications**

<u>Pin Number</u>	<u>Pin</u>	<u>Designator</u>
1	GND	- Power Supply
2	+VS	+ Power Supply

### **Typical Input Circuit**



### **Typical Output Circuit**



### **Digital Output Pin Assignments**

Bit Number	Pin Designator
1	OUT 01
2	OUT 02
3	OUT 03
4	OUT 04
5	OUT 05
6	OUT 06
7	OUT 07
8	OUT 08
9	INPUT 01
10	INPUT 02
11	INPUT 03
12	INPUT 04
13	INPUT 05
14	INPUT 06
15	INPUT 07
16	ISO. GND

### **Specifications**

Digital Outputs	8
-----------------	---

Output Bit	
Open-Collector	30Vdc, 100mA
Vsat	0.3V @ 100mA
Short Circuit	500mA max
Type	Sinking

### Digital Inputs 7

Input Bit	
Internal Pull-up	10K to +5Vdc
Max Voltage	+/-30Vdc
Logic '0'	<1.0Vdc
Logic '1'	>3.5Vdc

# Isolation

GND to IGND	500Vrms
-------------	---------

#### Watchdog Timer Range

Range	0 to 655.35 Sec
Resolution	0.35 Sec

#### Protocol TCP

Modbus TCP/IP

### Power Supply

voitage	+10-30Va
Power	1.0W

### Connectors

Spacing	3.81mm
Max Wire Size	14-24 AWG
Max Current	8 Amperes

#### LED Designators

LLD Dooignatoro	
01-15	Bit LO = On
F	Always Off
T	TxData
R	RxData

### LED Display

13)	9	(5)	$\odot$	
(14)	10	6	2	
<u>(15)</u>	11)	1	3	T
$\bigcirc$	12	(8)	4	R

Digital Input/Output LEDS

### 5.8.3 Fifteen Bit Digital Output Initial Factory Values

Module Parameter	<u>Value</u>
Slave Address*	1
Baud Rate*	9600
Parity Type*	None
Modbus Response Delay	3mS
Modbus Query Delay	0mS
Digital Output Initial Value	0x0000 = All Outputs Off
Watchdog Timer Low Word	0xffff, = Disabled

<sup>\* =</sup> These values should not be changed.

### 5.8.4 Fifteen Bit Digital Output Register Assignments

Register	Description	<u>Functions</u>	<u>Value</u>	<u>Description</u>
40001	Slave Address	R/WP	1-DF	Factory set to 0x0001.
40002	UART Setup	R/WP		Factory set to 0x0035 = 9600, 8, N, 1.
40003	Modbus Delays	R/WP	0-303F	Bits 0-7
				The Response Delay in milliseconds. This is
				required when the RS-485 adapter cannot tri-
				state immediately after the last character is
				transmitted from the host. Maximum value is
				63mS. Factory default value is 3.
				Bits 8-15
				The End of Query Delay in milliseconds (48mS
				max). This is an additional time that the module
				will wait prior to marking the end of the message.
				Slower host computers may not be able transmit
				a continuous message stream, thereby creating
				gaps between characters exceeding the normal
				3.5 character times limit. Factory default value is
				0.
				See Note 2.
40000	Coffware Varaion	Б		Factory set to 0x0003.
40033 40096	Software Version Watchdog Timer	R/WP	0.FFFF	Factory set, Code Version.  The interval of time in seconds that must elapse
40090	Interval	K/VVF	U.FFFF	after the last communication to the module or
	IIILEIVAI			since the power was applied, before the outputs
				are set to the Initial Value. The purpose of the
				Watchdog Timer is to force the digital outputs to a
				known safe value in the event of a host or
				communications link failure. The Watchdog Timer
				may be disabled by setting the value to 0xFFFF
				hex.
4000=	1 '' 12' 1	DAME	0.5555	Factory set to 0xFFFF.
40097	Initial Value	R/WP	0.FFFF	Starting condition of Coils 1-15. Bit #0 is Ch0.
				Initial Value bits set to Logic 1 will be initialized to
				the "On" state. Bits set to Logic 0 will be initialized to the "Off" state.
				Factory Set to 0x0000.
40241	Control Register	W		0 – Normal operation (NOP)
	2 2	••		1 – Remote Reset (write protected)
				2 – Write Enable
				3 – Synchronous Data sample
				5 – Init Host Com Setup

Discrete Coil (DI) Mapping Table			
Address (hex)	Channel #	Coil#	Using Function Codes 01 and 02
0	0	1	"
1	1	2	"
2	2	3	ű.
:			
Е	E	E	u

### **Functions:**

R Read Only
R/W Read/Write
WP Write-Protected

### Appendix A - Static IP Address

The D7000 series modules contain the ability to force a default static IP address. The default static IP address is unique to the model number and should only be used for configuration or performing a factory reset. A factory reset can be performed to return the module to the initial factory settings.

**Note:** The default static IP address mode should not be used in a production network environment.

To configure a D7000 series module to the default static IP address, please use the following steps below.

#### Steps:

- 1. Turn the power off to the module.
- 2. Position the module in front of you with the label facing up and the two mounting holes to the left and right sides of module.
- 3. Remove the four screws at the corners of the top cover. Then remove the top cover.
- 4. Locate the controller board inside the module that contains a three position pin strip and a jumper bar on top of it. Typically located to the lower right side of the package.



5. Move the jumper from the back two pins to the front two pins as seen in the picture below.



- 6. Turn on the power supply to the module.
- 7. Refer to "Table A.1 Static IP Address Table" below to determine the IP address by model number.
- 8. Use a web browser to browse to the correct IP address. For example, http://192.168.1.221 for a D7100.
- 9. Make all required changes to the module settings.
- 10. After all changes have been made, save them and remove power to the module.
- 11. Move the controller board jumper to the back position, place the cover back on the module and tighten down the four screws.

STATIC IP ADDRESS TABLE			
Model Number	IP Address	Subnet Mask	
D7100	192.168.1.221	255.255.255.0	
D7200	192.168.1.222	255.255.255.0	
D7300	192.168.1.223	255.255.255.0	
D7400	192.168.1.224	255.255.255.0	
D7500	192.168.1.225	255.255.255.0	
D7710	192.168.1.226	255.255.255.0	
D7720	192.168.1.227	255.255.255.0	
D7730	192.168.1.228	255.255.255.0	

Table A.1 – Static IP Address Table.

**Disclaimer:** This feature is available in devices displaying "Version 1.0.0.2" or higher at the bottom of each module web page.

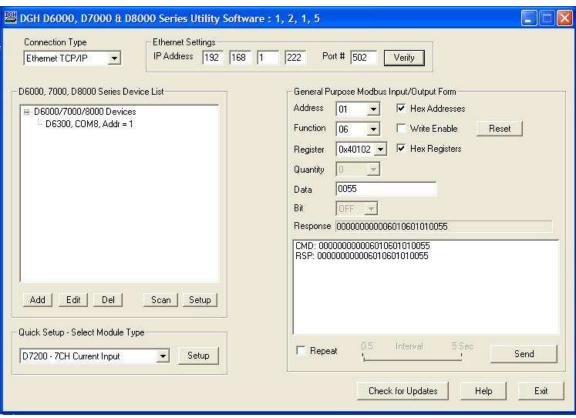
#### Appendix B - Factory Reset Device

The D7000 series modules contain an ethernet interface and internal controller board. The internal controller board contains EEPROM memory for storing network settings. The controller board also stores other customer specified values required to run the network features such as Peer-To-Peer, uploading values to cloud services, etc..

The D7000 series internal controller board can be factory reset to clear all the user specified network values, disable all of the network features and return the module network IP address to DHCP mode. Follow the steps below to perform the internal controller board factory reset.

#### Steps:

- Complete steps 1 through 7 in Appendix A to configure the D7000 for the default static IP address.
- 2. After the module is powered up, wait at least 30 seconds
- 3. Open the DGH D6000-D9000 Series Utility Software
- 4. Select an Ethernet Connection, enter the default IP address at the top of the screen.
- 5. Set the Device Address to 01, Function Code to 06 and the register Address to 0x40102 hex.
- 6. Enter a value of 55 in to the "data" field
- 7. Press the "Send" button as seen in Picture 1.0 below.



Picture 1.0 Factory Reset Screen Settings

- 8. The internal controller board will then be reset back to initial factory settings.
- 9. Perform Appendix A steps 10 and 11.
- 10. The factory reset process is now complete and the D7000 network IP mode is configured for DHCP mode.

**Disclaimer:** This feature is available in devices displaying "Version 1.0.0.2" or higher at the bottom of each module web page.

Notes: